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Magnetohydrodynamics Peristaltic Flow of a Couple- Stress with Varying Temperature and concentration for Jeffrey Fluid through a Flexible Porous Medium

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ABSTRACT

The topic of this paper is the peristaltic motion of a non-Newtonian Jeffrey fluid with couple stress across a porous medium inside a horizontal conduit. The unit is strained by a uniform magnetic field. It is taken into account the effects of viscous dissipation, internal heat generation, and radiation. This approach solves the equations of momentum, temperature, and velocity. The numerical formulas for temperature, axial velocity, and velocity are calculated as functions of the problem's physical parameters. Numerical calculations, as well as the effects of temperature and the inclined slanted magnetic field and concentration on the velocity equation, were conducted for this formula, and the results were shown on the channel wall. The results of the problem's physical parameters In a series of statistics, the effects of this formula are explained numerically and graphically.

1. Introduction

Peristaltic fluxes have piqued the interest of scientists. many rasearchers due to their weide Physiology and industry applications. The peristaltic system motility of blood in animals or human bodies has been studied by several authors. Peristaltic pumping has been found in many applications. Several researchers presented their scientific findings in the search for peristaltic flow of different flow geometries and were among the pioneersin this field to Latham[7]. In[10] and [8], they presented a comprehensive study of peristaltic flow fluid together with experimental results in which For this, the long wave approximation was used the analysis In a circular cylindrical tube, there is a peristaltic pumping problem. Furthermore, peristalsis exposed to magnetic field impacts is critical in the treatment of hyperthermia, arterial flow, cancer treatment, and other conditions. etc.; magnets can cause infections, ulcers, intestines and uterine diseases. Permeability has a big role and it has important applications in fluid movement, for example absorption of food in the intestine, extraction of oil from the ground, etc. Several researchers are involved in See [3], [5], [9], and [11] for research on the combined effect of a magnetic field and the presence of permeability in a fluid flow channel. The influence of temperature on the movement of fluids through a channel sparked interest, as most studies agreed that increasing the temperature increases the fluid's velocity The velocity of the fluid, on the other hand, fluctuates in an ambiguous manner in response to the concentration difference. For more information, see [4], [1], and [2]

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depending on where the fluid is in the channel. Hoseinzadeh and colleagues. [6] investigated the impact of the modified Darcy law on fluid flow in porous walls channels. The present analysis aims to discuss the effects of MHD on the couplestains of Jeffrey fluid through a medium porous cylindrical channel. To our knowledge, this attempt has not yet been explored in the presence of the magnetic field, the effect of temperature difference, and the double pressure concentration of a Jeffrey fluid flow in cylindrical coordinates through a porous channel.

2. Mathematical Formulation

Considering of flow a peristaltic a couple stress the incompressible Jeffrey fluid with the inclined slanted magnetic field and temperature with concentration of a circular pipe that is coaxial and uniform. The Jeffrey fluid is a non-Newtonian non-compressible fluid model that represents the real fluid when shear stress does not equal shear stress rate (or velocity gradient). The cylindrical coordinates are known when R is along the channel's radius and Z is parallel to the pipe's axes, as shown in figure 1.

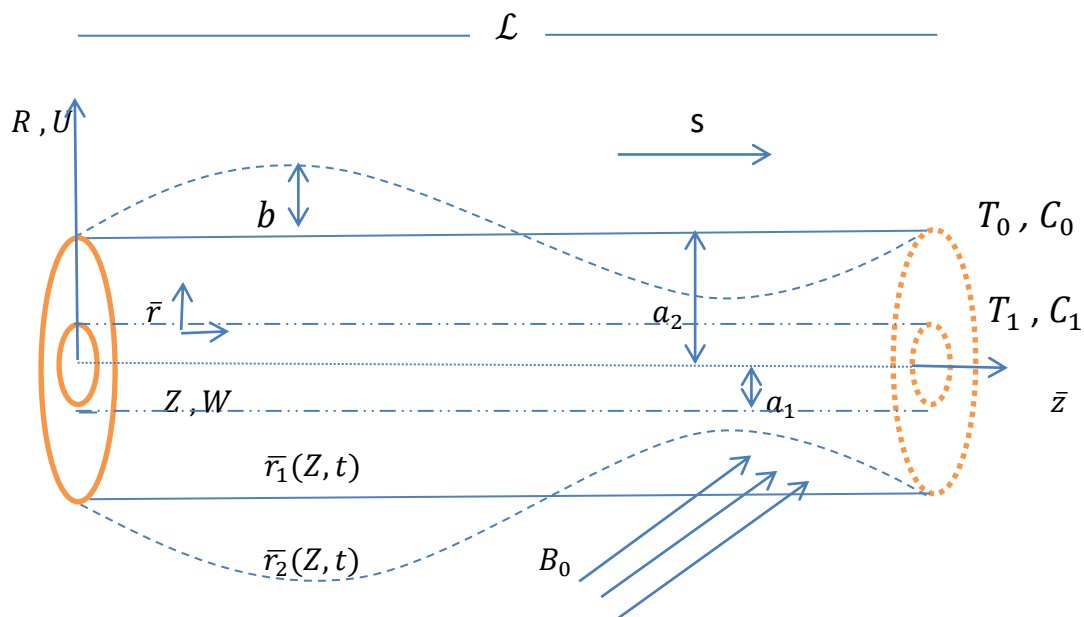


Figure. 1: The problem's geometry

The following is a description of the wall surface geometry:

$$\left. \begin{aligned} \bar{r} &= \bar{r}_1 = a_1 && \text{Inner wall} \\ \bar{r} &= \bar{r}_2(\bar{z}, \bar{t}) = a_2 + b \text{Sin}\left(\frac{2\pi}{L}(\bar{z} - s\bar{t})\right) && \text{Outer wall} \end{aligned} \right\} \tag{1}$$

Where a_1 is now the average radius of a channel that hasn't been affected, a_2 is now the average radius of a disturbed channel, b was its the peristaltic wave's amplitude, L was its wavelength, s was its speed of wave propagation, and \bar{t} is the time

3. Basic Equations

The governing equations are as follows:

The equation of continuity; $\nabla \bar{V} = 0,$ (2)

The equation of momentum with couple-stress fluid it's given by;

$$\rho(\bar{V} \cdot \nabla)\bar{V} = \nabla \bar{\sigma} + \mu_p \bar{J} \times \bar{B} - \frac{\mu}{K^*} \bar{V} + \rho g \beta_1 (T - T_0) + \rho g \beta_2 (C - C_0) - \bar{\zeta} \nabla^4 \bar{V}, \tag{3}$$

The equation of temperature it's given by;

$$T_s \cdot \rho (\bar{V} \cdot \nabla) T = T_c \cdot \nabla^2 T - \nabla \cdot Q_r - q(T - T_0), \tag{4}$$

The equation of concentration is given in:

$$(\bar{V} \cdot \nabla) C = D_m \nabla^2 C + \frac{D_m T_d}{T_m} \nabla^2 T. \tag{5}$$

When $\nabla^2 = \frac{1}{r} \frac{\partial}{\partial r} \left(r \frac{\partial}{\partial r} \right)$ is the ‘‘Laplace operator’’, $\nabla^4 = \nabla^2 (\nabla^2)$. Also \bar{V} is the velocity field, ρ ‘‘density’’, μ ‘‘dynamic viscosity’’ dependent on temperature, k^* ‘‘permeability’’, we observe that the magnetic field's effect is appear on the flow in the R and Z direction, J ‘‘induced current’’, $\bar{B} = (0, B_0 \sin(\omega), 0)$ the inclined magnetic field, μ_p ‘‘magnetic permeability’’, $\bar{\sigma}$ ‘‘Cauchy stress tensor’’ and $\bar{\zeta}$ is constant related to the couple stress. Also T and C are ‘‘temperature and concentration’’, T_c ‘‘thermal conductivity’’, T_s ‘‘specific heat capacity’’ at constant pressure, D_m ‘‘coefficient of mass diffusivity’’, ∇V the ‘‘fluid velocity gradient’’, T_m ‘‘mean fluid temperature’’, Q_r ‘‘radiation heat flux’’, q ‘‘heat generation’’ and T_d ‘‘thermal diffusion ratio’’.

For an incompressible Jeffrey fluid, the constitutive equations are as follows;

$$\bar{\sigma} = -\bar{P}\bar{I} + \bar{S}, \tag{6}$$

$$\bar{S} = \frac{\mu}{1+\lambda_1} (\bar{\gamma} + \lambda_2 \bar{\dot{\gamma}}). \tag{7}$$

where \bar{S} ‘‘extra stress tensor’’, \bar{P} ‘‘pressure’’, \bar{I} ‘‘identity tensor’’, λ_1 ‘‘ratio of relaxation to retardation times’’, $\bar{\gamma}$ ‘‘shear ratio’’, $\bar{\dot{\gamma}}$ ‘‘material derivative’’, and λ_2 ‘‘retardation time’’.

4. Method of solution

The two-frame coordinates transformations public and private are given by;

$$\bar{r} = \bar{R}, \bar{z} = \bar{Z}, \bar{u} = \bar{U}, \bar{w} = \bar{W} - s.$$

where (\bar{u}, \bar{w}) and (\bar{U}, \bar{W}) are the velocity components in public and private frames, respectively. The equations of motion are solved using these transforms;

$$\frac{\partial \bar{u}}{\partial \bar{t}} + \frac{\bar{u}}{\bar{r}} + \frac{\partial(\bar{w}+s)}{\partial \bar{z}} = 0, \tag{8}$$

$$\rho \left(\frac{\partial \bar{u}}{\partial \bar{t}} + \bar{u} \frac{\partial \bar{u}}{\partial \bar{r}} + (\bar{w} + s) \frac{\partial \bar{u}}{\partial \bar{z}} \right) = - \frac{\partial \bar{p}}{\partial \bar{r}} + \frac{1}{\bar{r}} \frac{\partial}{\partial \bar{r}} (\bar{r} \bar{S}_{\bar{r}\bar{r}}) + \frac{\partial}{\partial \bar{z}} (\bar{S}_{\bar{r}\bar{z}}) - \frac{\bar{S}_{\bar{\theta}\bar{\theta}}}{\bar{r}} - \sigma (B_0 \sin(\omega))^2 \bar{u} - \frac{\mu}{k^*} \bar{u} - \bar{\zeta} \bar{\nabla}^4 \bar{u}, \tag{9}$$

$$\rho \left(\frac{\partial(\bar{w}+s)}{\partial \bar{t}} + \bar{u} \frac{\partial(\bar{w}+s)}{\partial \bar{r}} + (\bar{w} + s) \frac{\partial(\bar{w}+s)}{\partial \bar{z}} \right) = - \frac{\partial \bar{p}}{\partial \bar{z}} + \frac{1}{\bar{r}} \frac{\partial}{\partial \bar{r}} (\bar{r} \bar{S}_{\bar{r}\bar{z}}) + \frac{\partial}{\partial \bar{z}} (\bar{S}_{\bar{z}\bar{z}}) + \rho g \beta_1 (T - T_0) + \rho g \beta_2 (C - C_0) - \sigma (B_0 \sin(\omega))^2 (\bar{w} + s) - \frac{\mu}{k^*} (\bar{w} + s) - \bar{\zeta} \bar{\nabla}^4 (\bar{w} + s), \tag{10}$$

$$\frac{\partial T}{\partial \bar{t}} + \bar{u} \frac{\partial T}{\partial \bar{r}} + (\bar{w} + s) \frac{\partial T}{\partial \bar{z}} = \frac{T_c}{T_s \rho} \left(\frac{\partial^2 T}{\partial \bar{r}^2} + \frac{1}{\bar{r}} \frac{\partial T}{\partial \bar{r}} + \frac{\partial^2 T}{\partial \bar{z}^2} \right) - \frac{16 \sigma_0 T_2^E}{3 k_0 T_s \rho} \frac{1}{\bar{r}} \frac{\partial}{\partial \bar{r}} \left(\bar{r} \frac{\partial T}{\partial \bar{r}} \right) - \frac{q}{T_s \rho} (T - T_0), \tag{11}$$

$$\frac{\partial C}{\partial \bar{t}} + \bar{u} \frac{\partial C}{\partial \bar{r}} + (\bar{w} + s) \frac{\partial C}{\partial \bar{z}} = D_m \left(\frac{\partial^2 C}{\partial \bar{r}^2} + \frac{1}{\bar{r}} \frac{\partial C}{\partial \bar{r}} + \frac{\partial^2 C}{\partial \bar{z}^2} \right) + \frac{D_m T_d}{T_m} \left(\frac{\partial^2 T}{\partial \bar{r}^2} + \frac{1}{\bar{r}} \frac{\partial T}{\partial \bar{r}} + \frac{\partial^2 T}{\partial \bar{z}^2} \right). \tag{12}$$

The relevant boundary conditions are:

$$\left. \begin{aligned} \bar{w} = -1, \bar{u} = 0, T = T_1, C = C_1 \text{ at } \bar{r} = r_1 = a_1, \\ \bar{w} = -1, \bar{u} = 0, T = T_0, C = C_0 \text{ at } \bar{r} = \bar{r}_2(\bar{z}, \bar{t}) = a_2 + b \sin\left(\frac{2\pi}{L}(\bar{z} - s\bar{t})\right). \end{aligned} \right\} \tag{13}$$

The governing equation for a flexible wall channel properties [5], is obtained as;

$$L^*(\bar{r}_2) = p - p_0 = \left(A \frac{\partial^4}{\partial \bar{z}^4} - N \frac{\partial^2}{\partial \bar{z}^2} + m \frac{\partial^2}{\partial \bar{t}^2} + C \frac{\partial}{\partial \bar{t}} + K_L \right) (\bar{r}_2) \tag{14}$$

where A is the wall's flexural rigidity, N is the longitudinal tension per unit width, m is the mass per unit area, C is the coefficient of viscous damping and K_L is spring stiffness and p_0 is the pressure on the wall's outside surface caused by muscle tension.

The following dimensionless transformations were conferred in order to simplify the motion's governing equations;

$$\left. \begin{aligned} u &= \frac{\bar{u}\mathcal{L}}{a_2s}, w = \frac{\bar{w}}{s}, r = \frac{\bar{r}}{a_2}, z = \frac{\bar{z}}{\mathcal{L}}, S = \frac{a_2\bar{S}}{\mu s}, \delta = \frac{a_2}{\mathcal{L}}, Da = \frac{k}{a_2^2}, \\ \mathcal{H} &= \frac{T-T_0}{T_1-T_0}, C = \frac{C-C_0}{C_1-C_0}, Rn = \frac{K_0 T_s \mu}{4T_2^E \sigma_0}, p = \frac{a_2^2 \bar{p}}{\mu s \mathcal{L}}, M_1^2 = \frac{\sigma a_2^2 B_0^2}{\mu} \sin^2(\bar{\omega}), \\ r_1 &= \frac{\bar{r}_1}{a_2} = \varepsilon < 1, r_2 = \frac{\bar{r}_2}{a_2} = 1 + \Phi \sin(2\pi\bar{z}), \alpha = \bar{\alpha} a_2 = \sqrt{\frac{\mu}{\zeta}} a_2, \\ Pr &= \frac{\mu T_s}{T_c}, \Omega = \frac{qa_2^2}{\mu T_s}, Sr = \frac{\rho D_m T_d (T_1 - T_0)}{\mu T_m (C_1 - C_0)}, Sc = \frac{\mu}{\rho D_m}, t = \frac{s\bar{t}}{\mathcal{L}}, \\ Gr &= \frac{\rho g \beta_1 a_2^2 (T_1 - T_0)}{\mu s}, Gc = \frac{\rho g \beta_2 a_2^2 (C_1 - C_0)}{\mu s}, \Phi = \frac{b}{a_2}, Re = \frac{\rho s a_2}{\mu}, \bar{\nabla} = \frac{\nabla}{a_2}. \end{aligned} \right\} \quad (15)$$

where Φ “amplitude ratio”, $\bar{\alpha}$ “couple stress” The ratio of the tube radius (constant) to the material characteristic length is a fluid parameter. ($\sqrt{\mu/\zeta}$, has the dimension of length), Re “Reynolds number”, Pr “Prandtl number”, Da “Darcy number”, Rn “thermal radiation parameter”, Sc “Schmidt number”, Sr “Soret number”, Gr “thermal Grashof number”, Gc “Solutal Grashof number”, M_1^2 “magnetic parameter”, δ “dimensionless wave number” and Ω “heat source/sink parameter”.

Introducing non-dimensional analysis (15) for equations (8)-(14) then dropping over-bars, the pervious governing equations and boundary conditions can be rewritten in the following form;

$$\left(\frac{s}{\mathcal{L}}\right) \left(\frac{\partial u}{\partial r} + \frac{u}{r} + \frac{\partial w}{\partial z}\right) = 0, \quad (16)$$

$$Re \delta^3 \left(\frac{\partial u}{\partial t} + u \frac{\partial u}{\partial r} + (w + 1) \frac{\partial u}{\partial z}\right) = -\frac{\partial p}{\partial r} + \delta \frac{1}{r} \frac{\partial}{\partial r} (r S_{rr}) + \delta^2 \frac{\partial}{\partial z} (S_{rz}) - \delta \frac{S_{\theta\theta}}{r} - \frac{\delta^2}{Da} u - \frac{\delta^2}{\alpha^2} \nabla^4 u - \delta^2 M_1^2 u, \quad (17)$$

$$Re \delta \left(\frac{\partial w}{\partial t} + u \frac{\partial w}{\partial r} + (w + 1) \frac{\partial w}{\partial z}\right) = -\frac{\partial p}{\partial z} + \frac{1}{r} S_{rz} + \frac{\partial}{\partial r} (S_{rz}) + \delta \frac{\partial}{\partial z} (S_{zz}) - \left(M_1^2 + \frac{1}{Da}\right) w + Gr\mathcal{H} + GcC - \left(M_1^2 + \frac{1}{Da}\right) - \frac{1}{\alpha^2} \nabla^4 (w + 1), \quad (18)$$

$$Re \delta \left(\frac{\partial T}{\partial t} + u \frac{\partial \mathcal{H}}{\partial r} + (w + 1) \frac{\partial \mathcal{H}}{\partial z}\right) = \frac{1}{Pr} \left(\frac{\partial^2 \mathcal{H}}{\partial r^2} + \frac{1}{r} \frac{\partial \mathcal{H}}{\partial r} + \delta^2 \frac{\partial^2 \mathcal{H}}{\partial z^2}\right) - \frac{4}{3Rn} \frac{1}{r} \frac{\partial}{\partial r} \left(r \frac{\partial \mathcal{H}}{\partial r}\right) - \Omega \mathcal{H}, \quad (19)$$

$$\delta Re \left(\frac{\partial C}{\partial t} + u \frac{\partial C}{\partial r} + (w + 1) \frac{\partial C}{\partial z}\right) = \frac{1}{Sc} \left(\frac{\partial^2 C}{\partial r^2} + \frac{1}{r} \frac{\partial C}{\partial r} + \delta^2 \frac{\partial^2 C}{\partial z^2}\right) + Sr \left(\frac{\partial^2 \mathcal{H}}{\partial r^2} + \frac{1}{r} \frac{\partial \mathcal{H}}{\partial r} + \delta^2 \frac{\partial^2 \mathcal{H}}{\partial z^2}\right). \quad (20)$$

Where

$$S_{rr} = \frac{2\delta}{1+\lambda_1} \left[1 + \frac{s\lambda_2\delta}{a_2} \left(\frac{\partial}{\partial t} + u \frac{\partial}{\partial r} + (w + 1) \frac{\partial}{\partial z}\right)\right] \left(\frac{\partial u}{\partial r}\right) \quad (21)$$

$$S_{rz} = \frac{1}{1+\lambda_1} \left[1 + \frac{s\lambda_2\delta}{a_2} \left(\frac{\partial}{\partial t} + u \frac{\partial}{\partial r} + (w + 1) \frac{\partial}{\partial z}\right)\right] \left(\frac{\partial w}{\partial r} + \delta^2 \frac{\partial u}{\partial z}\right) \quad (22)$$

$$S_{\theta\theta} = \frac{2\delta}{1+\lambda_1} \left[u + \frac{s\lambda_2\delta}{a_2} \left(\frac{1}{r} \frac{\partial u}{\partial t} + \frac{u}{r} \frac{\partial u}{\partial r} - \frac{u^2}{r^2} + (w + 1) \frac{1}{r} \frac{\partial u}{\partial z}\right)\right] \quad (23)$$

$$S_{zz} = \frac{2\delta}{1+\lambda_1} \left[1 + \frac{s\lambda_2\delta}{a_2} \left(\frac{\partial}{\partial t} + u \frac{\partial}{\partial r} + (w + 1) \frac{\partial}{\partial z}\right)\right] \left(\frac{\partial w}{\partial z}\right) \quad (24)$$

with corresponding dimensional boundary conditions are;

$$\begin{aligned} w = -1, u = 0, C = 1, \mathcal{H} = 1 & \quad \text{at} \quad r = r_1 = \varepsilon, \\ w = -1, u = 0, C = 0, \mathcal{H} = 0 & \quad \text{at} \quad r = r_2 = 1 + \delta \sin(2\pi(z - t)). \end{aligned} \tag{25}$$

Continuity of stress means that the **pressure** at the fluid-wall interface must be the same as the pressure acting on the fluid at $r = r_2$. The dynamic boundary conditions at the complaint walls are obtained using the z momentum equation;

$$\begin{aligned} L_1 \frac{\partial^5(h)}{\partial z^5} - L_2 \frac{\partial^3(h)}{\partial z^3} + L_3 \frac{\partial^3(h)}{\partial z \partial t^2} + L_4 \frac{\partial^2(h)}{\partial z \partial t} + L_5 \frac{\partial(h)}{\partial z} = \frac{1}{r} S_{rz} + \frac{\partial}{\partial r} (S_{rz}) - \left(M_1^2 + \frac{1}{D_a}\right) w + \\ Gr\mathcal{H} + GcC - \left(M_1^2 + \frac{1}{D_a}\right) - \frac{1}{\alpha^2} \nabla^4(w + 1). \end{aligned} \tag{26}$$

Where $L_1 = \frac{Aa_2^3}{\mu s L^5}$, $L_2 = -\frac{Na_2^3}{\mu s L^3}$, $L_3 = \frac{msa_2^3}{\mu L^3}$, $L_4 = \frac{Ca_2^3}{\mu L^2}$, and $L_5 = \frac{K_L a_2^3}{\mu s L}$, whereas L_1 is the flexural rigidity of the wall, L_2 is the per-unit-width longitudinal tension, L_3 is the mass per square meter, L_4 is the viscous damping coefficient, and L_5 is the stiffness of a spring, respectively.

Because it appears impossible to answer the problem in its generalized form, we will limit our analysis to the assumption of a tiny dimensionless wave number ($\delta \ll 1$).

In other words, we discovered the approximate long-wavelength. Equations (16)-(26) result from this assumption:

$$\frac{\partial u}{\partial r} + \frac{u}{r} + \frac{\partial w}{\partial z} = 0, \tag{27}$$

$$\frac{\partial p}{\partial r} = 0, \tag{28}$$

$$\frac{\partial p}{\partial z} = \frac{1}{r} S_{rz} + \frac{\partial}{\partial r} (S_{rz}) - \left(M_1^2 + \frac{1}{D_a}\right) w + Gr\mathcal{H} + GcC - \left(M_1^2 + \frac{1}{D_a}\right) - \frac{1}{\alpha^2} \nabla^4(w + 1), \tag{29}$$

$$\left(\frac{1}{Pr} - \frac{4}{3Rn}\right) \frac{1}{r} \frac{\partial}{\partial r} \left(r \frac{\partial \mathcal{H}}{\partial r}\right) - \Omega \mathcal{H} = 0, \tag{30}$$

$$\frac{1}{Sc} \left(\frac{\partial^2 C}{\partial r^2} + \frac{1}{r} \frac{\partial C}{\partial r}\right) = -Sr \left(\frac{\partial^2 \mathcal{H}}{\partial r^2} + \frac{1}{r} \frac{\partial \mathcal{H}}{\partial r}\right), \tag{31}$$

$$\begin{aligned} L_1 \frac{\partial^5(h)}{\partial z^5} - L_2 \frac{\partial^3(h)}{\partial z^3} + L_3 \frac{\partial^3(h)}{\partial z \partial t^2} + L_4 \frac{\partial^2(h)}{\partial z \partial t} + L_5 \frac{\partial(h)}{\partial z} = \frac{1}{r} S_{rz} + \frac{\partial}{\partial r} (S_{rz}) - \left(M_1^2 + \frac{1}{D_a}\right) w + \\ Gr\mathcal{H} + GcC - \left(M_1^2 + \frac{1}{D_a}\right) - \frac{1}{\alpha^2} \nabla^4(w + 1). \end{aligned} \tag{32}$$

Where

$$S_{rr} = S_{\theta\theta} = S_{zz} = 0 \text{ and } S_{rz} = \frac{1}{1+\lambda_1} \left(\frac{\partial w}{\partial r}\right) \tag{33}$$

Replecing S_{rz} from equation (33) in to equation (32), we have:

$$\begin{aligned} \frac{1}{\alpha^2} \nabla^4 w - \frac{1}{1+\lambda_1} \frac{1}{r} \frac{\partial}{\partial r} \left(r \frac{\partial w}{\partial r}\right) + \left(M_1^2 + \frac{1}{D_a}\right) w = - \left(L_1 \frac{\partial^5(h)}{\partial z^5} - L_2 \frac{\partial^3(h)}{\partial z^3} + L_3 \frac{\partial^3(h)}{\partial z \partial t^2} + L_4 \frac{\partial^2(h)}{\partial z \partial t} + \right. \\ \left. L_5 \frac{\partial(h)}{\partial z} + \left(M_1^2 + \frac{1}{D_a}\right) - Gr\mathcal{H} - GcC\right). \end{aligned} \tag{34}$$

We shall get the following dimensionless boundary conditions if the elements of a pair stress tensor at the wall remain zero:

$$\begin{aligned} w = -1, \frac{\partial^2 w}{\partial r^2} - \frac{\alpha}{r} \frac{\partial w}{\partial r} = 0 & \quad \text{at} \quad r = \varepsilon, \\ w = -1, \frac{\partial^2 w}{\partial r^2} - \frac{\alpha}{r} \frac{\partial w}{\partial r} = 0 & \quad \text{at} \quad r = r_2. \end{aligned} \tag{35}$$

Where $\alpha = \frac{\mu}{\zeta}$ is a couplestress fluid parameter (μ and ζ are constants associated with the couplestress, when $\alpha \rightarrow 1$ (i.e. $\mu \rightarrow \zeta$) no couple stress effect [9].

5. Solutions of the Problem

5.1 "Temperature and Concentration" Functions

Rewrite the temperature equation (30) as follow;

$$r^2 \frac{\partial^2 \mathcal{H}}{\partial r^2} + r \frac{\partial \mathcal{H}}{\partial r} + Ar^2 \mathcal{H} = 0, \tag{36}$$

where $A = -\frac{3\Omega Pr Rn}{3Rn - 4Pr}$. Equation (36) is a zero-order modified Bessel equation. The answer to the equation(36) with boundary conditions $\mathcal{H}(r_1) = 1, \mathcal{H}(r_2) = 0$ is;

$$\mathcal{H} = B_1 J_0[r\sqrt{A}] + B_2 Y_0[r\sqrt{A}] \tag{37}$$

Where $B_1 = \frac{Y_0[h\sqrt{A}]}{J_0[\epsilon\sqrt{A}]Y_0[h\sqrt{A}] - J_0[h\sqrt{A}]Y_0[\epsilon\sqrt{A}]}$ and $B_2 = \frac{J_0[h\sqrt{A}]}{J_0[h\sqrt{A}]Y_0[\epsilon\sqrt{A}] - J_0[\epsilon\sqrt{A}]Y_0[h\sqrt{A}]}$.

The equation of concentration (31), can be written as;

$$\frac{1}{r} \frac{\partial}{\partial r} \left(r \frac{\partial C}{\partial r} \right) = -Sc Sr \frac{1}{r} \frac{\partial}{\partial r} \left(r \frac{\partial \mathcal{H}}{\partial r} \right). \tag{38}$$

The general solution of equation (38) is:

$$C = -Sc Sr \mathcal{H} + B_3 \ln(r) + B_4. \tag{39}$$

Where $B_3 = \frac{1 + S_c S_r}{\ln(\epsilon / (1 + \phi \sin(2\pi z)))}$ and $B_4 = -B_3 \ln(1 + \phi \sin(2\pi z))$

5.2 Momentum Function

Rewrite the momentum equation (34) as follow;

$$w = B_1 I_0(\beta r \sqrt{|s_1|}) + B_2 K_0(\beta r \sqrt{|s_1|}) + B_3 I_0(\beta r \sqrt{|s_2|}) + B_4 K_0(\beta r \sqrt{|s_2|}) - \frac{1}{M_1^2 + \frac{1}{Da}} \left(L_1(32\pi^5 \phi \cos[2\pi(z-t)]) - L_2(-8\pi^3 \phi \cos[2\pi(z-t)]) + L_3(-8\pi^3 \phi \cos[2\pi(z-t)]) + L_4(4\pi^2 \phi \sin[2\pi(z-t)]) + L_5(2\pi \phi \cos[2\pi(z-t)]) + \left(M_1^2 + \frac{1}{Da} \right) - Gr \mathcal{H} - GcC \right). \tag{40}$$

where $\beta^4 = \frac{\alpha^2}{Da}$, $s_1 = -\frac{c_1}{\beta^2} - \sqrt{\left(\frac{c_1}{\beta^2}\right)^2 - 1}$, $s_2 = -\frac{c_1}{\beta^2} + \sqrt{\left(\frac{c_1}{\beta^2}\right)^2 - 1}$ and $c_1 = \frac{\alpha^2}{2(1+\lambda_1)}$ with condition $\frac{c_1}{\beta^2} > 1$. Also I_0, K_0 are "the modified Bessel functions" of the first and second kind of zero order. By using the Mathematical12 we have a constants B_1, B_2, B_3 and B_4 in our program and boundary conditions (29).

5.3 Stream Function

The corresponding functions of stream ($w = \frac{1}{r} \frac{\partial \psi}{\partial r}$) is;

$$\psi = \int r \left\{ B_1 I_0(\ell r \sqrt{|s_1|}) + B_2 K_0(\ell r \sqrt{|s_1|}) + B_3 I_0(\ell r \sqrt{|s_2|}) + B_4 K_0(\ell r \sqrt{|s_2|}) - \frac{1}{M_1^2 + \frac{1}{Da}} \left(L_1(32\pi^5 \phi \cos[2\pi(z-t)]) - L_2(-8\pi^3 \phi \cos[2\pi(z-t)]) + L_3(-8\pi^3 \phi \cos[2\pi(z-t)]) + L_4(4\pi^2 \phi \sin[2\pi(z-t)]) + L_5(2\pi \phi \cos[2\pi(z-t)]) + \left(M_1^2 + \frac{1}{Da} \right) - Gr\mathcal{H} - GcC \right) \right\} dr \quad (41)$$

So that

$$\psi = \frac{r^2}{2} \left(\frac{L_1(32\pi^5 \phi \cos[2\pi(z-t)]) - L_2(-8\pi^3 \phi \cos[2\pi(z-t)]) + L_3(-8\pi^3 \phi \cos[2\pi(z-t)]) + L_4(4\pi^2 \phi \sin[2\pi(z-t)]) + L_5(2\pi \phi \cos[2\pi(z-t)]) + \left(M_1^2 + \frac{1}{Da} \right) - Gr\mathcal{H} - GcC}{\left(M_1^2 + \frac{1}{Da} \right)^2} \right) - \frac{B_2 r K_1(r \ell \sqrt{|s_1|})}{\ell \sqrt{|s_1|}} - \frac{B_4 r K_1(r \ell \sqrt{|s_2|})}{\ell \sqrt{|s_2|}} + \frac{1}{2} B_1 r^2 {}_0\tilde{F}_1 \left[2; \frac{r^2 (\ell \sqrt{|s_1|})^2}{4} \right] + \frac{1}{2} B_3 r^2 {}_0\tilde{F}_1 \left[2; \frac{r^2 (\ell \sqrt{|s_2|})^2}{4} \right] \quad (42)$$

where K_1 “is the modified Bessel function” of the second kind and $({}_0\tilde{F}_1)$ regular hypergeometric function.

6. Discussion and The Numerical Results

The numerical and computational results for the problem of an incompressible non-Newtonian Jeffrey fluid via porous media with heat and concentration with an inclination in the magnetic field are addressed with illustrations in this part. Figures 2–48 illustrate the key features of peristaltic flow of a couple-stress fluid through a porous material. The “MATHEMATICA 12” application was used for numerical findings and graphics.

6.1 Temperature Distribution

Basis on equation (37), figures 2-7 illustrates an effect the parameters $\Omega, \varepsilon, \phi, Rn, t$ and Pr on the function of a fluid temperature \mathcal{H} vs. r . Figures 2-6, shows that a temperature of the fluid increases with increasing the parameters $\Omega, \varepsilon, Rn, t$ and Pr , respectively, while Figure 7 demonstrates that the temperature of a fluid decreases with increasing the parameter ϕ .

6.2 Concentration Distribution

On the basis of equation (39), figures 8-15, illustrates parameter effects $\Omega, \varepsilon, \phi, Sr, Sc, Rn, Pr$ and t on the concentration function C . Figure 8, we notice that the concentration of fluid increases with increasing of Ω . In figure 9, we notice the effect of the parameter ε on the concentration increases with increasing of ε . By figure 10, We found the concentration decreases with increasing ϕ . Figure 11, concentration change increases with increasing Sr . Figure 12, we notice that C increases with increasing Sc . Figure 13, the concentration increases with increasing Rn . Figure 14, concentration change increases with increasing Pr . Figure 15, the concentration increases with increasing t .

6.3 Velocity Distribution

On the basis of equation (40), figures 16-35 illustrates parameter results $\varepsilon, \phi, \lambda_1, L_5, L_4, L_3, L_1, t, L_2, Da, \alpha, \zeta, M, Gr, \Omega, Pr, Rn, Sr, Sc$ and Gc on the distribution of velocity w vs. r . Figure 16, demonstrates the effect of the parameters ε on the velocity distribution w vs. r . It's found the velocity w increases with increasing ε at $r > 0.12$, when there's w decrease with increase of ε at $r < 0.12$. Figure 17, shows the behavior of w under the variation of ϕ , we notice the increase in the velocity when increasing ϕ in the region $r < 0.2$ and the decrease in the velocity with increasing ϕ in the region $r > 0.2$. Figure 18, we notice the rotation of the

effect of the parameter λ_1 , it is increase in the velocity when increasing λ_1 in the region $r > 0.2$ and w decrease in the velocity with increasing λ_1 in the region $r < 0.2$. Figure 19, we notice the rotation of the effect of the parameter L_5 , it is increase in the velocity when increasing L_5 in the region $r < 0.2$ and w decrease in the velocity with increasing L_5 in the region $r > 0.2$. Figure 20, we notice the rotation of the effect of the parameter L_4 , it is increase in the velocity when increasing L_4 in the region $r < 0.2$ and w decrease in the velocity with increasing L_4 in the region $r > 0.2$. Figure 21, shows the behavior of w under the variation of L_3 , we notice the increase in the velocity when increasing L_3 in the region $r > 0.2$ and the decrease in the velocity with increasing L_3 in the region $r < 0.2$. Figure 22, shows the behavior of w under the variation of L_1 , we notice the increase in the velocity when increasing L_1 in the region $r < 0.2$ and the decrease in the velocity with increasing L_1 in the region $r > 0.2$. Figure 23, shows the behavior of w under the variation of t , we notice the increase in the velocity when increasing t in the region $r > 0.2$ and the decrease in the velocity with increasing t in the region $r < 0.2$. Figure 24, shows the behavior of w under the variation of L_2 , we notice the increase in the velocity when increasing L_2 in the region $r < 0.2$ and the decrease in the velocity with increasing L_2 in the region $r > 0.2$. In the figure 25, shows the behavior of w under the variation of Da , we notice the increase in the velocity when increasing Da in the region $r < 0.2$ and the decrease in the velocity with increasing Da in the region $r > 0.2$. In the figure 26, shows the behavior of w under the variation of α , we notice the increase in the velocity when increasing α in the region $r < 0.2$ and the decrease in the velocity with increasing α in the region $r > 0.2$. In the figure 27, shows the behavior of w under the variation of ζ , we notice the decrease in the velocity when increasing ζ . Figure 28, shows the behavior of w under the variation of M , we notice the increase in the velocity when increasing M in the region $r > 0.2$ and the decrease in the velocity with increasing M in the region $r < 0.2$. Figure 29, shows the behavior of w under the variation of Gr , we notice the decrease in the velocity when increasing Gr in the region $r < 0.2$ and the increase in the velocity with increasing Gr in the region $r > 0.2$. Figure 30, shows the behavior of w under the variation of Ω , we notice the decrease in the velocity when increasing Ω . In the figure 31, shows the behavior of w under the variation of Pr , we notice the decrease in the velocity when increasing Pr . We notice the effect of Rn , on the velocity function in figure 32, shows the behavior of w is similar to the effect of M in figure 28. As figures 33 and 34 shows an decreases in velocity with the increase of both parameters Sr and Sc . We notice the effect of Gc on the velocity function in figure 35, w is similar to the effect of M in figure 28.

6.4 Trapping Phenomena

The development of an internally circulating bolus of fluid by closed streamlines is known as trapping, and this trapped bolus is pushed forward with the peristaltic wave. According to equation (42), the effects ε , \emptyset , λ_1 , L_5 , L_4 , L_3 , L_1 , t , L_2 , Da , α , ζ , M , Gr , Ω , Pr , Rn , Sr , Sc and Gc on trapping can be seen through 36 - 48. Figure 36, shows that the volume of the trapped bolus lowered with the increase ε gradually in the middle of the channel. In the figure 37, shows that the size of the trapped bolus located in the center of the channel increases with the increase \emptyset . By figure 38, the volume of the trapped bolus decreases when increase λ_1 gradually in middle of channel. By figure 39, we notice trapped bolus, in the center of the channel increase with increase L_5 the bolus will turn into a wave and L_5 has a weak impact. In figure 40, with the increases L_4 gradually the size of the trapped bolus increases at the middle. In figure 41, the volume of the trapped bolus its beginning to grow in the center with increase of L_3 . Figure 42, show effect the parameter L_1 on trapped bolus, as that caused the bolus to grow in the center of the channel with increase of L_1 . In figure 43, the volume of the trapped bolus in the middle decreases with t increase and the wave will turn into a bolus. In figure 44, the volume of the trapped bolus in the wave at the center increases with L_2 increase and we get waves of bolus. In figure 45, the volume of the trapped bolus in the wave increases with Da increase and the bolus will turn into a wave. In figure 46, with α increasing we get increase the volume of the

trapped bolus in the wave at the center. By figure 47, with ζ increasing we get increase the volume of the trapped bolus in the wave at the center. Figure 48, the volume of the trapped bolus in the middle decreases with M increase and the wave will turn into a bolus. And finally, we note that the following parameters are $Gr, \Omega, Pr, Rn, Sr, Sc$ and Gc very weak.

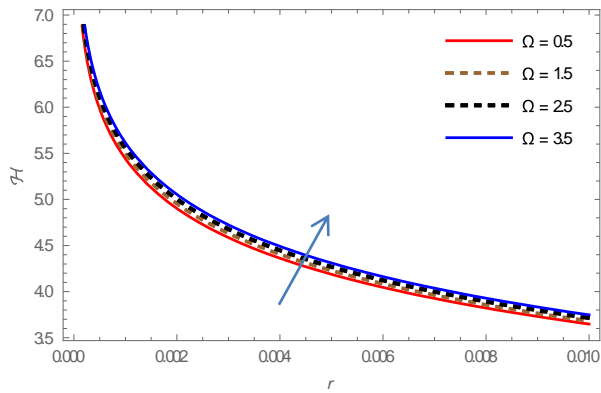


Figure 2: Temperature variations \mathcal{H} vs. r at $\epsilon = 0.3, \phi = 0.3, Rn = 0.1, Pr = 2, t = 0.05, z = 0.1$.

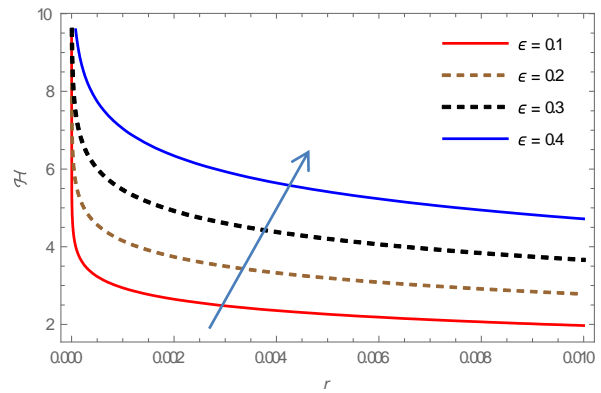


Figure 3: Temperature variations \mathcal{H} vs. r at $\Omega = 0.9, \phi = 0.3, Rn = 0.1, Pr = 2, t = 0.05, z = 0.1$.

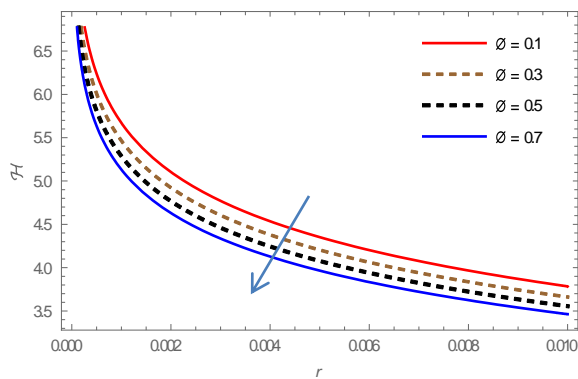


Figure 4: Temperature variations \mathcal{H} vs. r at $\Omega = 0.9, \epsilon = 0.3, Rn = 0.1, Pr = 2, t = 0.05, z = 0.1$.

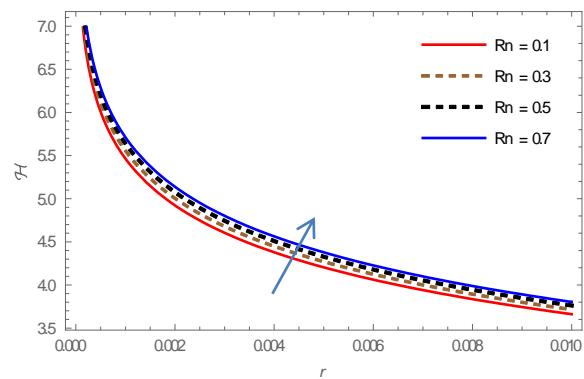


Figure 5: Temperature variations \mathcal{H} vs. r at $\Omega = 0.9, \phi = 0.3, \epsilon = 0.3, Pr = 2, t = 0.05, z = 0.1$.

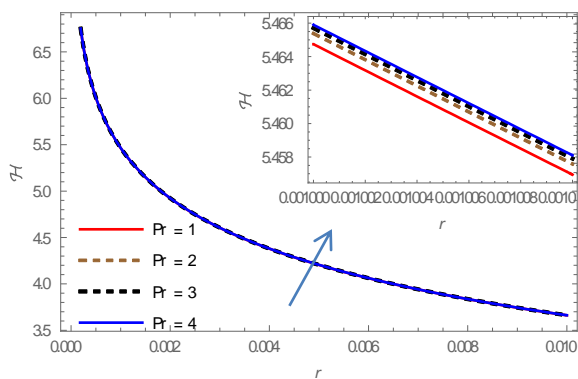


Figure 6: Temperature variations \mathcal{H} vs. r at $\Omega = 0.9, \epsilon = 0.3, Rn = 0.1, \phi = 0.3, t = 0.05, z = 0.1$.

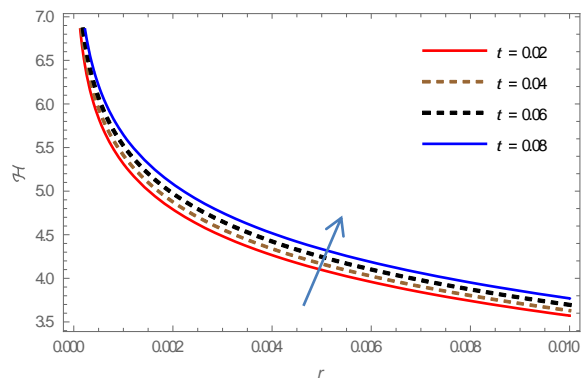


Figure 7: Temperature variations \mathcal{H} vs. r at $\Omega = 0.9, \epsilon = 0.3, Rn = 0.1, Pr = 2, \phi = 0.3, z = 0.1$.

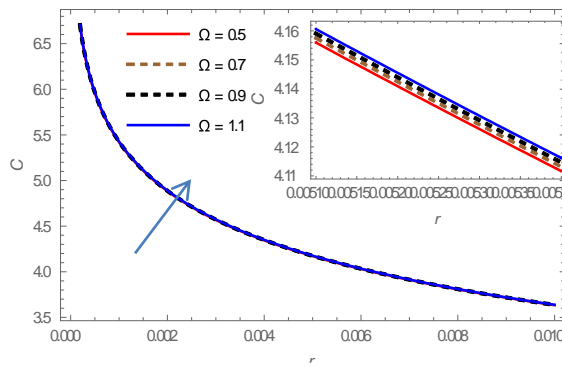


Figure 8: concentration variation C vs. r at $\varepsilon = 0.2, \phi = 0.2, Sr = 0.6, Sc = 0.5, Rn = 0.5, Pr = 2, t = 0.05, z = 0.1$.

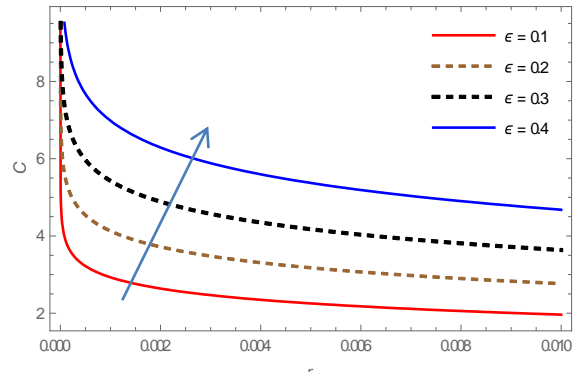


Figure 9: concentration variation C vs. r at $\Omega = 0.2, \phi = 0.2, Sr = 0.6, Sc = 0.5, Rn = 0.5, Pr = 2, t = 0.05, z = 0.1$.

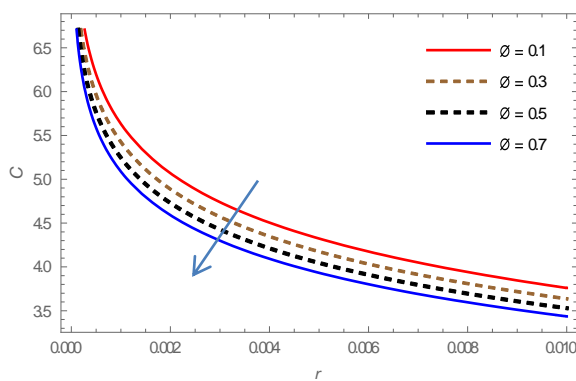


Figure 10: concentration variation C vs. r at $\Omega = 0.2, \varepsilon = 0.2, Sr = 0.6, Sc = 0.5, Rn = 0.5, Pr = 2, t = 0.05, z = 0.1$.

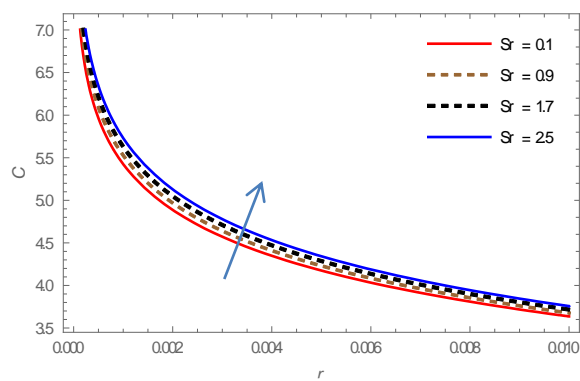


Figure 11: concentration variation C vs. r at $\Omega = 0.2, \varepsilon = 0.2, \phi = 0.2, Sc = 0.5, Rn = 0.5, Pr = 2, t = 0.05, z = 0.1$.

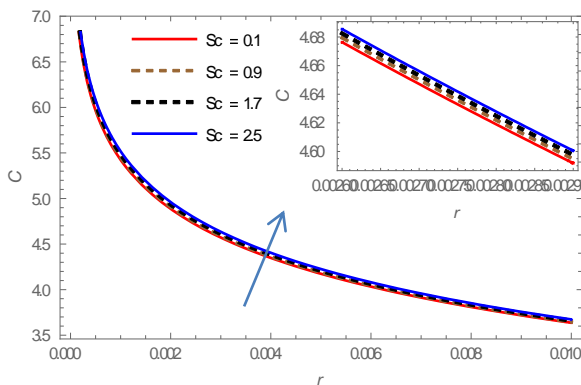


Figure 12: concentration variation C vs. r at $\Omega = 0.2, \varepsilon = 0.2, \phi = 0.2, Sr = 0.6, Rn = 0.5, Pr = 2, t = 0.05, z = 0.1$.

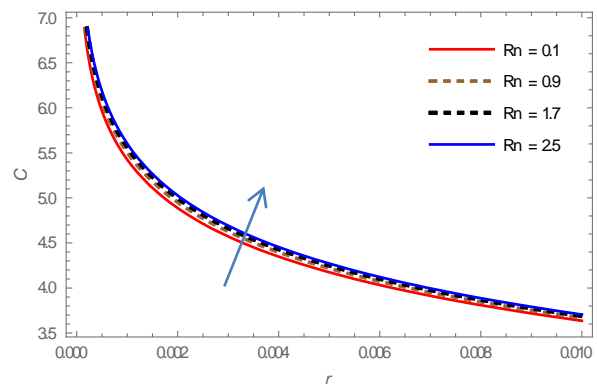


Figure 13: concentration variation C vs. r at $\Omega = 0.2, \varepsilon = 0.2, \phi = 0.2, Sr = 0.6, Sc = 0.5, Pr = 2, t = 0.05, z = 0.1$.

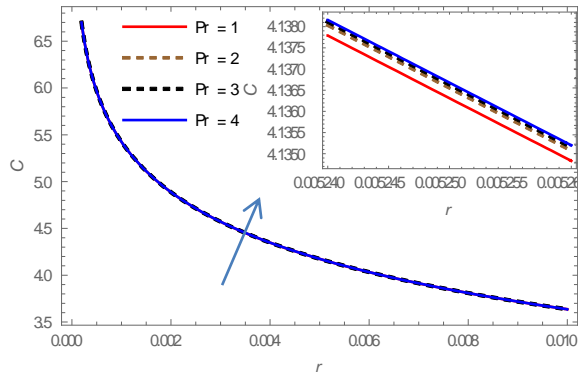


Figure 14: concentration variation C vs. r at $\Omega = 0.2$, $\varepsilon = 0.2$, $\phi = 0.2$, $Sr = 0.6$, $Sc = 0.5$, $Rn = 0.5$, $t = 0.05$, $z = 0.1$.

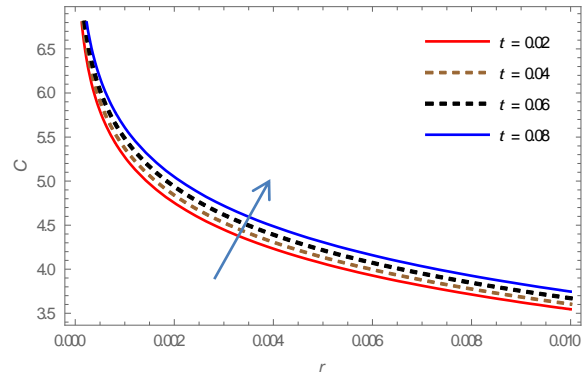


Figure 15: concentration variation C vs. r at $\Omega = 0.2$, $\varepsilon = 0.2$, $\phi = 0.2$, $Sr = 0.6$, $Sc = 0.5$, $Rn = 0.5$, $Pr = 2$, $z = 0.1$.

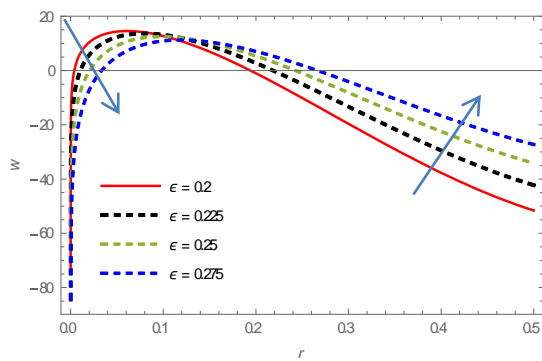


Figure 16: velocity distribution for various values of ε with $\phi = 0.2$, $\lambda_1 = 0.1$, $L_5 = 0.1$, $L_4 = 0.5$, $L_3 = 0.1$, $L_1 = 0.1$, $t = 0.05$, $L_2 = 0.5$, $Da = 0.9$, $\alpha = 3.75$, $\zeta = 0.5$, $M = 1.1$, $Gr = 2$, $\Omega = 0.9$, $Pr = 2$, $Rn = 0.5$, $Sr = 0.6$, $Sc = 0.5$, $Gc = 1$, $z = 0.1$.

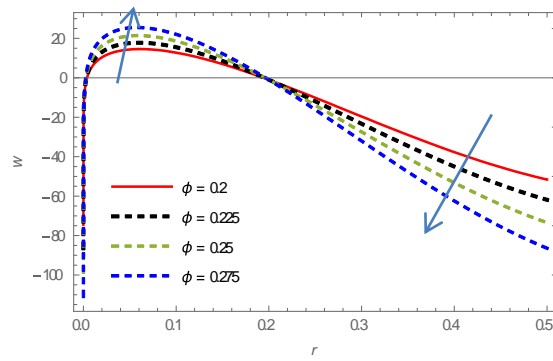


Figure 17: velocity distribution for various values of ϕ with $\varepsilon = 0.2$, $\lambda_1 = 0.1$, $L_5 = 0.1$, $L_4 = 0.5$, $L_3 = 0.1$, $L_1 = 0.1$, $t = 0.05$, $L_2 = 0.5$, $Da = 0.9$, $\alpha = 3.75$, $\zeta = 0.5$, $M = 1.1$, $Gr = 2$, $\Omega = 0.9$, $Pr = 2$, $Rn = 0.5$, $Sr = 0.6$, $Sc = 0.5$, $Gc = 1$, $z = 0.1$.

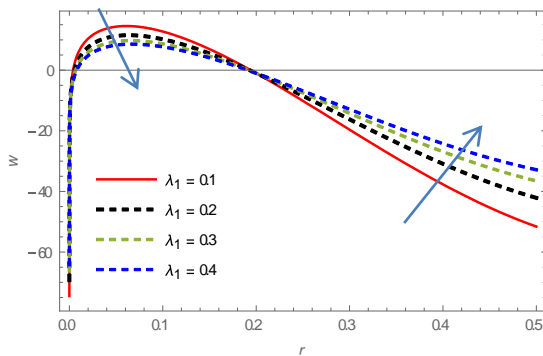


Figure 18: velocity distribution for various values of λ_1 with $\varepsilon = 0.2$, $\phi = 0.2$, $L_5 = 0.1$, $L_4 = 0.5$, $L_3 = 0.1$, $L_1 = 0.1$, $t = 0.05$, $L_2 = 0.5$, $Da = 0.9$, $\alpha = 3.75$, $\zeta = 0.5$, $M = 1.1$, $Gr = 2$, $\Omega = 0.9$, $Pr = 2$, $Rn = 0.5$, $Sr = 0.6$, $Sc = 0.5$, $Gc = 1$, $z = 0.1$.

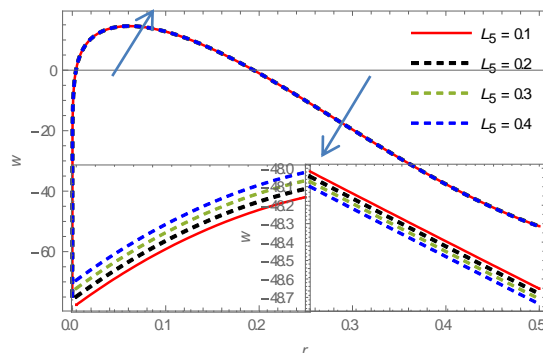


Figure 19: velocity distribution for various values of L_5 with $\varepsilon = 0.2$, $\phi = 0.2$, $\lambda_1 = 0.1$, $L_4 = 0.5$, $L_3 = 0.1$, $L_1 = 0.1$, $t = 0.05$, $L_2 = 0.5$, $Da = 0.9$, $\alpha = 3.75$, $\zeta = 0.5$, $M = 1.1$, $Gr = 2$, $\Omega = 0.9$, $Pr = 2$, $Rn = 0.5$, $Sr = 0.6$, $Sc = 0.5$, $Gc = 1$, $z = 0.1$.

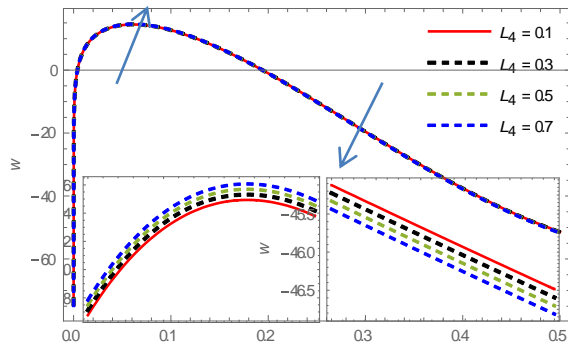


Figure 20: velocity distribution for various values of L_4 with $\varepsilon = 0.2$, $\phi = 0.2$, $\lambda_1 = 0.1$, $L_5 = 0.1$, $L_3 = 0.1$, $L_1 = 0.1$, $t = 0.05$, $L_2 = 0.5$, $Da = 0.9$, $\alpha = 3.75$, $\zeta = 0.5$, $M = 1.1$, $Gr = 2$, $\Omega = 0.9$, $Pr = 2$, $Rn = 0.5$, $Sr = 0.6$, $Sc = 0.5$, $Gc = 1$, $z = 0.1$.

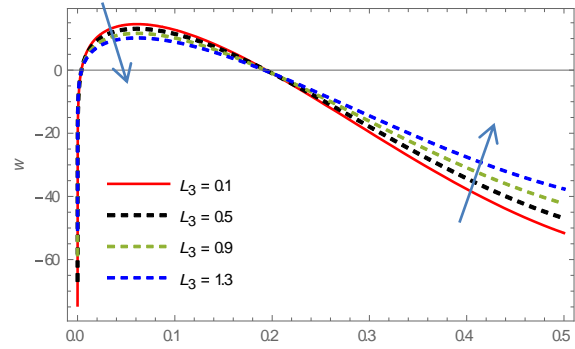


Figure 21: velocity distribution for various values of L_3 with $\varepsilon = 0.2$, $\phi = 0.2$, $\lambda_1 = 0.1$, $L_5 = 0.1$, $L_4 = 0.5$, $L_1 = 0.1$, $t = 0.05$, $L_2 = 0.5$, $Da = 0.9$, $\alpha = 3.75$, $\zeta = 0.5$, $M = 1.1$, $Gr = 2$, $\Omega = 0.9$, $Pr = 2$, $Rn = 0.5$, $Sr = 0.6$, $Sc = 0.5$, $Gc = 1$, $z = 0.1$.

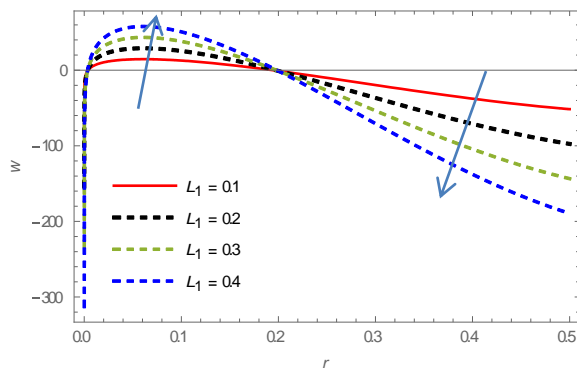


Figure 22: velocity distribution for various values of L_1 with $\varepsilon = 0.2$, $\phi = 0.2$, $\lambda_1 = 0.1$, $L_5 = 0.1$, $L_4 = 0.5$, $L_3 = 0.1$, $t = 0.05$, $L_2 = 0.5$, $Da = 0.9$, $\alpha = 3.75$, $\zeta = 0.5$, $M = 1.1$, $Gr = 2$, $\Omega = 0.9$, $Pr = 2$, $Rn = 0.5$, $Sr = 0.6$, $Sc = 0.5$, $Gc = 1$, $z = 0.1$.

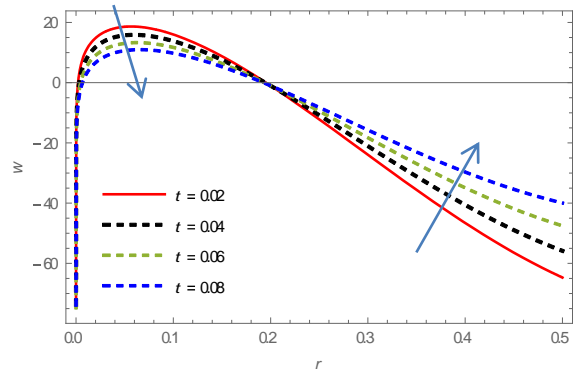


Figure 23: velocity distribution for various values of t with $\varepsilon = 0.2$, $\phi = 0.2$, $\lambda_1 = 0.1$, $L_5 = 0.1$, $L_4 = 0.5$, $L_3 = 0.1$, $L_1 = 0.1$, $L_2 = 0.5$, $Da = 0.9$, $\alpha = 3.75$, $\zeta = 0.5$, $M = 1.1$, $Gr = 2$, $\Omega = 0.9$, $Pr = 2$, $Rn = 0.5$, $Sr = 0.6$, $Sc = 0.5$, $Gc = 1$, $z = 0.1$.

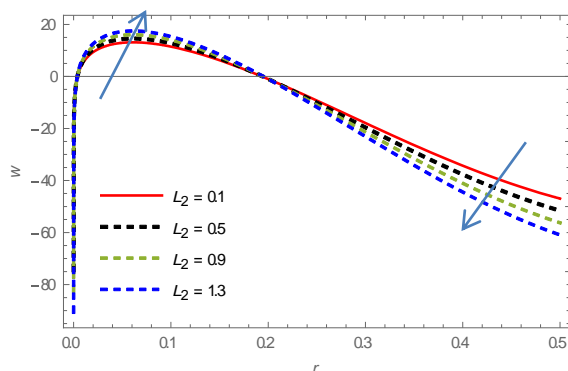


Figure 24: velocity distribution for various values of L_2 with $\varepsilon = 0.2$, $\phi = 0.2$, $\lambda_1 = 0.1$, $L_5 = 0.1$, $L_4 = 0.5$, $L_3 = 0.1$, $L_1 = 0.1$, $t = 0.05$, $Da = 0.9$, $\alpha = 3.75$, $\zeta = 0.5$, $M = 1.1$, $Gr = 2$, $\Omega = 0.9$, $Pr = 2$, $Rn = 0.5$, $Sr = 0.6$, $Sc = 0.5$, $Gc = 1$, $z = 0.1$.

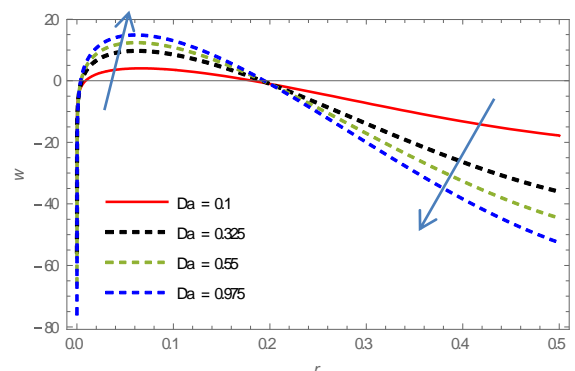


Figure 25: velocity distribution for various values of Da with $\varepsilon = 0.2$, $\phi = 0.2$, $\lambda_1 = 0.1$, $L_5 = 0.1$, $L_4 = 0.5$, $L_3 = 0.1$, $L_1 = 0.1$, $t = 0.05$, $L_2 = 0.5$, $\alpha = 3.75$, $\zeta = 0.5$, $M = 1.1$, $Gr = 2$, $\Omega = 0.9$, $Pr = 2$, $Rn = 0.5$, $Sr = 0.6$, $Sc = 0.5$, $Gc = 1$, $z = 0.1$.

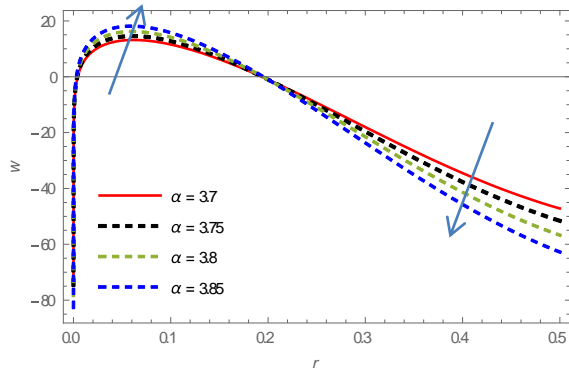


Figure 26: velocity distribution for various values of α with $\varepsilon = 0.2, \phi = 0.2, \lambda_1 = 0.1, L_5 = 0.1, L_4 = 0.5, L_3 = 0.1, L_1 = 0.1, t = 0.05, L_2 = 0.5, Da = 0.9, \zeta = 0.5, M = 1.1, Gr = 2, \Omega = 0.9, Pr = 2, Rn = 0.5, Sr = 0.6, Sc = 0.5, Gc = 1, z = 0.1$.

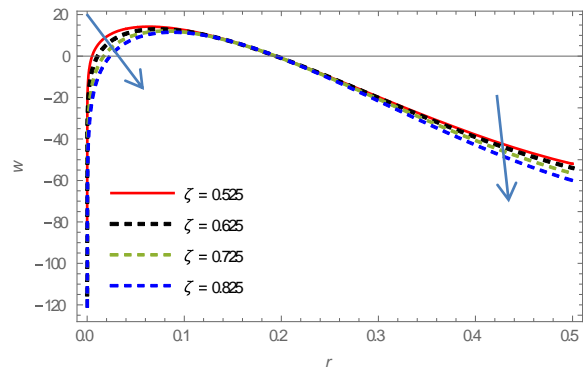


Figure 27: velocity distribution for various values of ζ with $\varepsilon = 0.2, \phi = 0.2, \lambda_1 = 0.1, L_5 = 0.1, L_4 = 0.5, L_3 = 0.1, L_1 = 0.1, t = 0.05, L_2 = 0.5, Da = 0.9, \alpha = 3.75, M = 1.1, Gr = 2, \Omega = 0.9, Pr = 2, Rn = 0.5, Sr = 0.6, Sc = 0.5, Gc = 1, z = 0.1$.

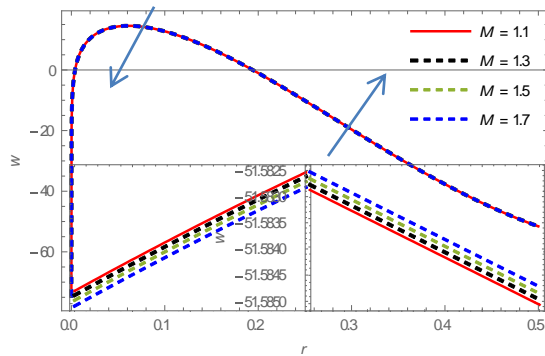


Figure 28: velocity distribution for various values of M with $\varepsilon = 0.2, \phi = 0.2, \lambda_1 = 0.1, L_5 = 0.1, L_4 = 0.5, L_3 = 0.1, L_1 = 0.1, t = 0.05, L_2 = 0.5, Da = 0.9, \alpha = 3.75, \zeta = 0.5, Gr = 2, \Omega = 0.9, Pr = 2, Rn = 0.5, Sr = 0.6, Sc = 0.5, Gc = 1, z = 0.1$.

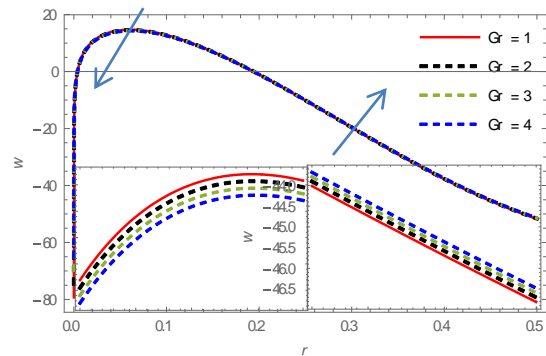


Figure 29: velocity distribution for various values of Gr with $\varepsilon = 0.2, \phi = 0.2, \lambda_1 = 0.1, L_5 = 0.1, L_4 = 0.5, L_3 = 0.1, L_1 = 0.1, t = 0.05, L_2 = 0.5, Da = 0.9, \alpha = 3.75, \zeta = 0.5, M = 1.1, \Omega = 0.9, Pr = 2, Rn = 0.5, Sr = 0.6, Sc = 0.5, Gc = 1, z = 0.1$.

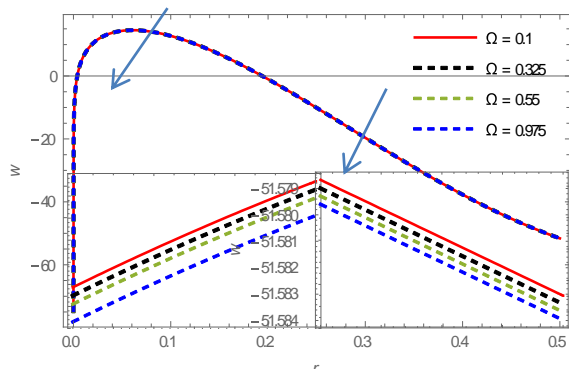


Figure 30: velocity distribution for various values of Ω with $\varepsilon = 0.2, \phi = 0.2, \lambda_1 = 0.1, L_5 = 0.1, L_4 = 0.5, L_3 = 0.1, L_1 = 0.1, t = 0.05, L_2 = 0.5, Da = 0.9, \alpha = 3.75, \zeta = 0.5, M = 1.1, Gr = 2, Pr = 2, Rn = 0.5, Sr = 0.6, Sc = 0.5, Gc = 1, z = 0.1$.

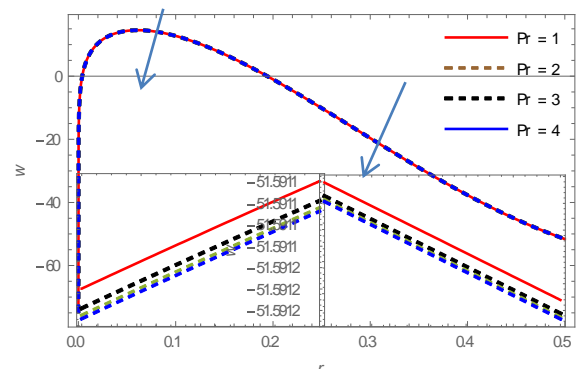


Figure 31: velocity distribution for various values of Pr with $\varepsilon = 0.2, \phi = 0.2, \lambda_1 = 0.1, L_5 = 0.1, L_4 = 0.5, L_3 = 0.1, L_1 = 0.1, t = 0.05, L_2 = 0.5, Da = 0.9, \alpha = 3.75, \zeta = 0.5, M = 1.1, Gr = 2, \Omega = 0.9, Rn = 0.5, Sr = 0.6, Sc = 0.5, Gc = 1, z = 0.1$.

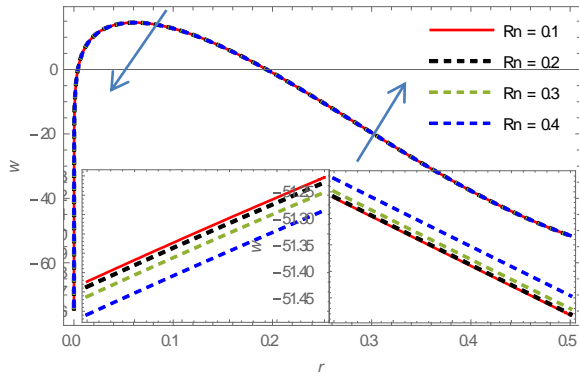


Figure 32: velocity distribution for various values of Rn with $\varepsilon = 0.2, \phi = 0.2, \lambda_1 = 0.1, L_5 = 0.1, L_4 = 0.5, L_3 = 0.1, L_1 = 0.1, t = 0.05, L_2 = 0.5, Da = 0.9, \alpha = 3.75, \zeta = 0.5, M = 1.1, Gr = 2, \Omega = 0.9, Pr = 2, Sr = 0.6, Sc = 0.5, Gc = 1, z = 0.1$.

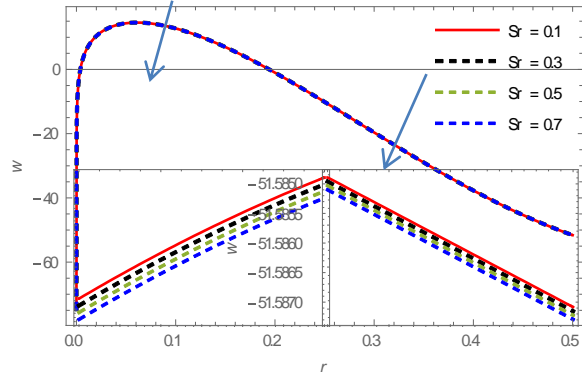


Figure 33: velocity distribution for various values of Sr with $\varepsilon = 0.2, \phi = 0.2, \lambda_1 = 0.1, L_5 = 0.1, L_4 = 0.5, L_3 = 0.1, L_1 = 0.1, t = 0.05, L_2 = 0.5, Da = 0.9, \alpha = 3.75, \zeta = 0.5, M = 1.1, Gr = 2, \Omega = 0.9, Pr = 2, Rn = 0.5, Sc = 0.5, Gc = 1, z = 0.1$.

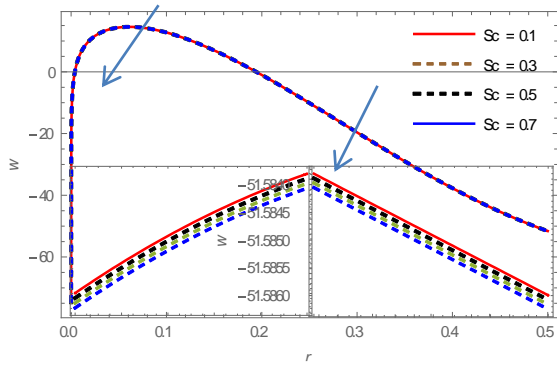


Figure 34: velocity distribution for various values of Sc with $\varepsilon = 0.2, \phi = 0.2, \lambda_1 = 0.1, L_5 = 0.1, L_4 = 0.5, L_3 = 0.1, L_1 = 0.1, t = 0.05, L_2 = 0.5, Da = 0.9, \alpha = 3.75, \zeta = 0.5, M = 1.1, Gr = 2, \Omega = 0.9, Pr = 2, Rn = 0.5, Sr = 0.6, Gc = 1, z = 0.1$.

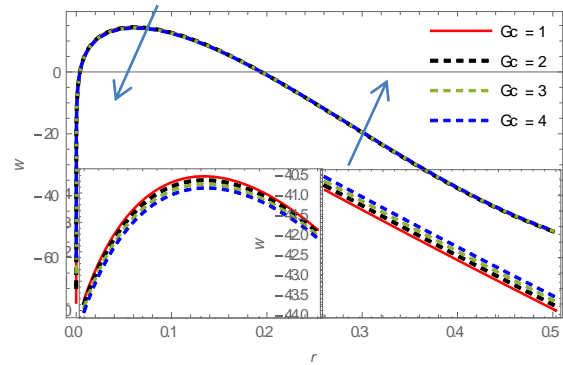


Figure 35: velocity distribution for various values of Gc with $\varepsilon = 0.2, \phi = 0.2, \lambda_1 = 0.1, L_5 = 0.1, L_4 = 0.5, L_3 = 0.1, L_1 = 0.1, t = 0.05, L_2 = 0.5, Da = 0.9, \alpha = 3.75, \zeta = 0.5, M = 1.1, Gr = 2, \Omega = 0.9, Pr = 2, Rn = 0.5, Sr = 0.6, Sc = 0.5, z = 0.1$.

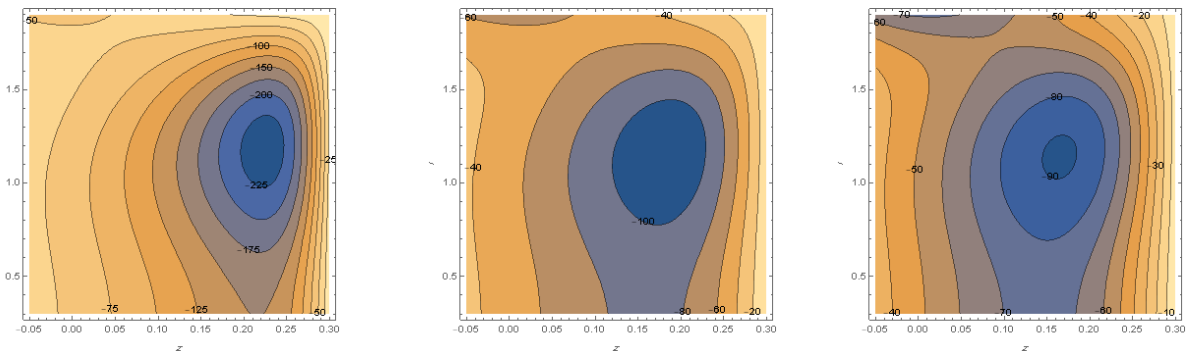


Figure 36: Wave frame streamlines for different values of $\varepsilon = \{0.1, 0.2, 0.3\}$ at $\phi = 0.2, \lambda_1 = 0.1, L_5 = 0.1, L_4 = 0.5, L_3 = 0.1, L_1 = 0.1, t = 0.05, L_2 = 0.5, Da = 0.9, \alpha = 3.75, \zeta = 0.5, M = 1.1, Gr = 2, \Omega = 0.9, Pr = 2, Rn = 0.5, Sr = 0.6, Sc = 0.5, Gc = 1$.

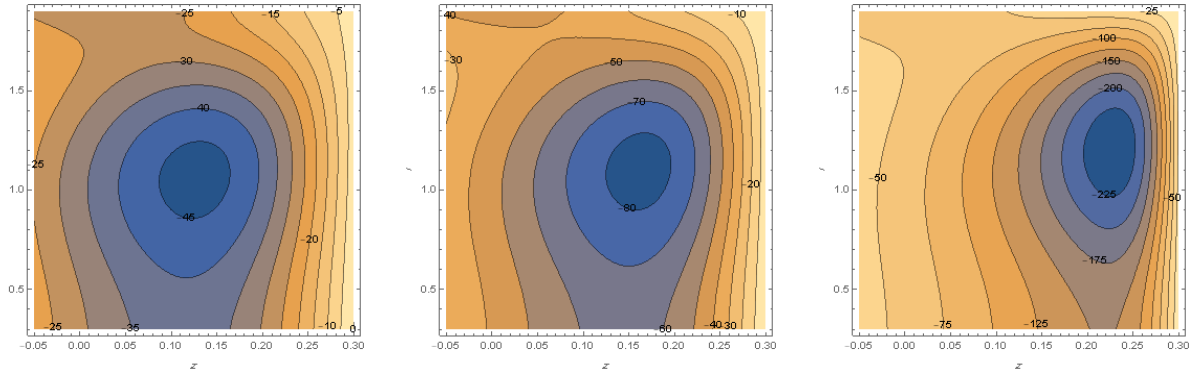


Figure 37: Wave frame streamlines for different values of $\phi = \{0.1, 0.15, 0.225\}$ at $\varepsilon = 0.2$, $\lambda_1 = 0.1$, $L_5 = 0.1$, $L_4 = 0.5$, $L_3 = 0.1$, $L_1 = 0.1$, $t = 0.05$, $L_2 = 0.5$, $Da = 0.9$, $\alpha = 3.75$, $\zeta = 0.5$, $M = 1.1$, $Gr = 2$, $\Omega = 0.9$, $Pr = 2$, $Rn = 0.5$, $Sr = 0.6$, $Sc = 0.5$, $Gc = 1$.

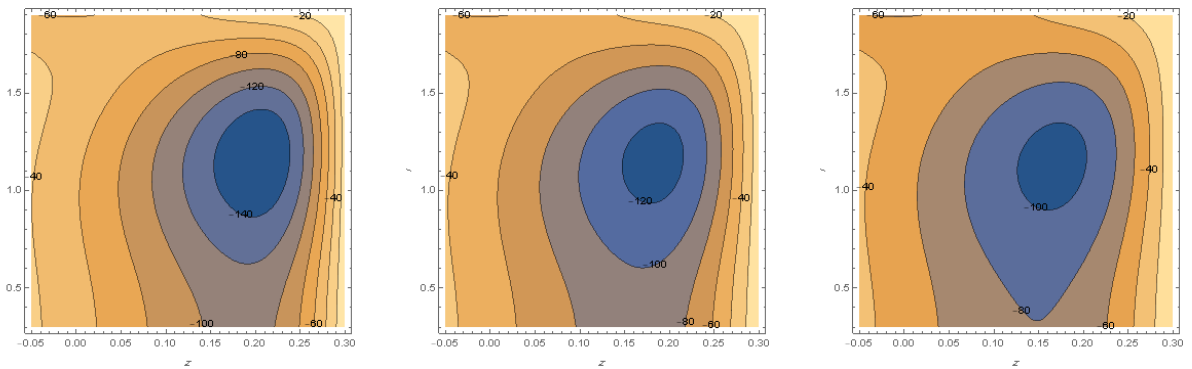


Figure 38: Wave frame streamlines for different values of $\lambda_1 = \{0.1, 0.15, 0.225\}$ at $\varepsilon = 0.2$, $\phi = 0.2$, $L_5 = 0.1$, $L_4 = 0.5$, $L_3 = 0.1$, $L_1 = 0.1$, $t = 0.05$, $L_2 = 0.5$, $Da = 0.9$, $\alpha = 3.75$, $\zeta = 0.5$, $M = 1.1$, $Gr = 2$, $\Omega = 0.9$, $Pr = 2$, $Rn = 0.5$, $Sr = 0.6$, $Sc = 0.5$, $Gc = 1$.

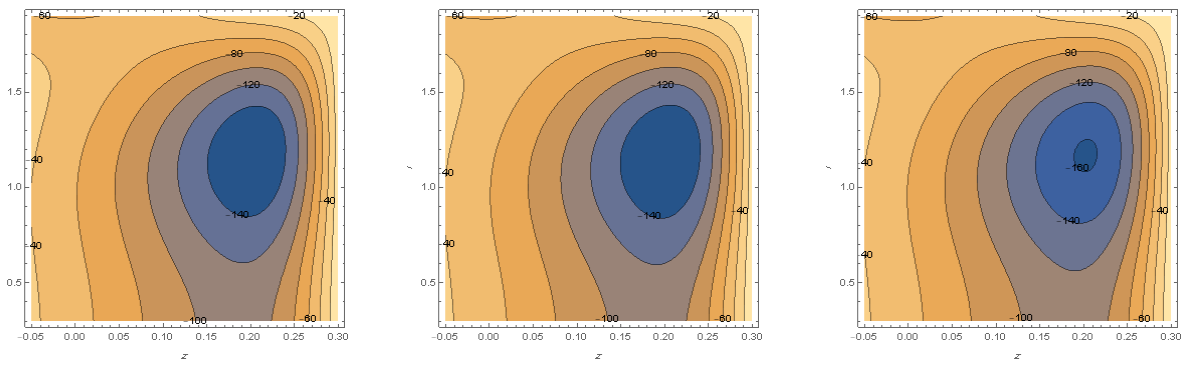


Figure 39: Wave frame streamlines for different values of $L_5 = \{2, 4, 6\}$ at $\varepsilon = 0.2$, $\phi = 0.2$, $\lambda_1 = 0.1$, $L_4 = 0.5$, $L_3 = 0.1$, $L_1 = 0.1$, $t = 0.05$, $L_2 = 0.5$, $Da = 0.9$, $\alpha = 3.75$, $\zeta = 0.5$, $M = 1.1$, $Gr = 2$, $\Omega = 0.9$, $Pr = 2$, $Rn = 0.5$, $Sr = 0.6$, $Sc = 0.5$, $Gc = 1$.

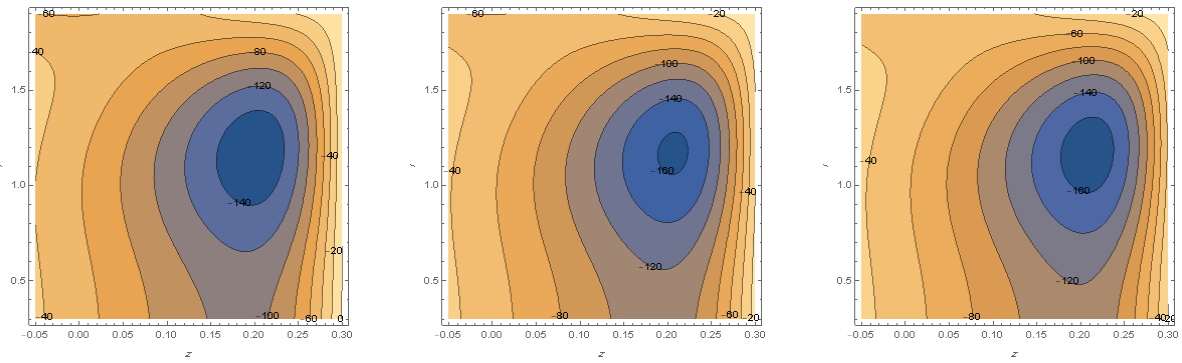


Figure 40: Wave frame streamlines for different values of $L_4 = \{0.1, 1.3, 2.1\}$ at $\varepsilon = 0.2, \phi = 0.2, \lambda_1 = 0.1, L_5 = 0.1, L_3 = 0.1, L_1 = 0.1, t = 0.05, L_2 = 0.5, Da = 0.9, \alpha = 3.75, \zeta = 0.5, M = 1.1, Gr = 2, \Omega = 0.9, Pr = 2, Rn = 0.5, Sr = 0.6, Sc = 0.5, Gc = 1$.

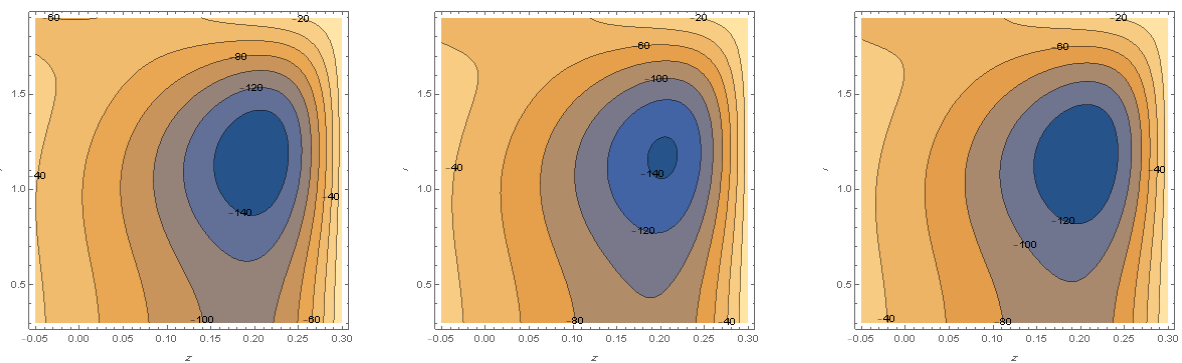


Figure 41: Wave frame streamlines for different values of $L_3 = \{0.1, 0.5, 0.625\}$ at $\varepsilon = 0.2, \phi = 0.2, \lambda_1 = 0.1, L_5 = 0.1, L_4 = 0.5, L_1 = 0.1, t = 0.05, L_2 = 0.5, Da = 0.9, \alpha = 3.75, \zeta = 0.5, M = 1.1, Gr = 2, \Omega = 0.9, Pr = 2, Rn = 0.5, Sr = 0.6, Sc = 0.5, Gc = 1$.

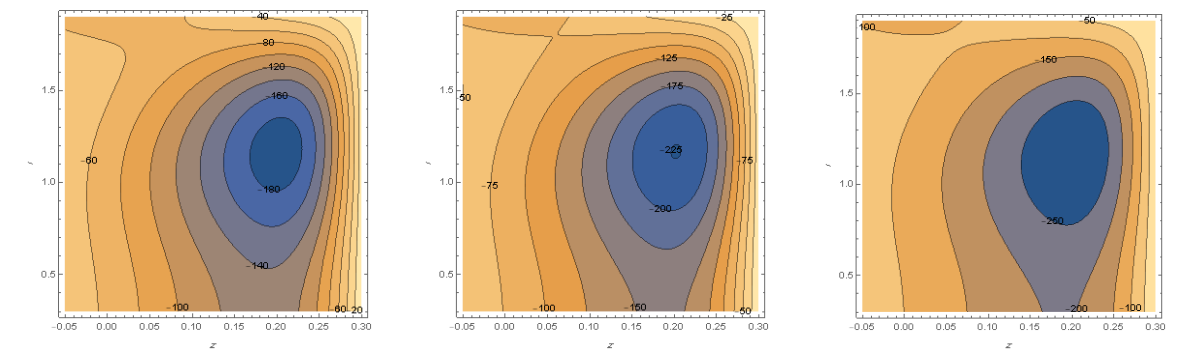


Figure 42: Wave frame streamlines for different values of $L_1 = \{0.125, 0.15, 0.175\}$ at $\varepsilon = 0.2, \phi = 0.2, \lambda_1 = 0.1, L_5 = 0.1, L_4 = 0.5, L_3 = 0.1, t = 0.05, L_2 = 0.5, Da = 0.9, \alpha = 3.75, \zeta = 0.5, M = 1.1, Gr = 2, \Omega = 0.9, Pr = 2, Rn = 0.5, Sr = 0.6, Sc = 0.5, Gc = 1$.

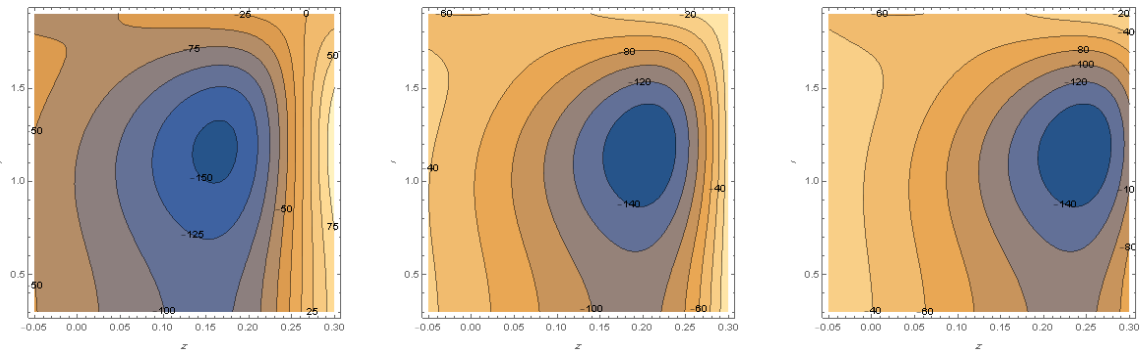


Figure 43: Wave frame streamlines for different values of $t = \{0.01, 0.05, 0.07\}$ at $\varepsilon = 0.2$, $\phi = 0.2$, $\lambda_1 = 0.1$, $L_5 = 0.1$, $L_4 = 0.5$, $L_3 = 0.1$, $L_1 = 0.1$, $L_2 = 0.5$, $Da = 0.9$, $\alpha = 3.75$, $\zeta = 0.5$, $M = 1.1$, $Gr = 2$, $\Omega = 0.9$, $Pr = 2$, $Rn = 0.5$, $Sr = 0.6$, $Sc = 0.5$, $Gc = 1$.

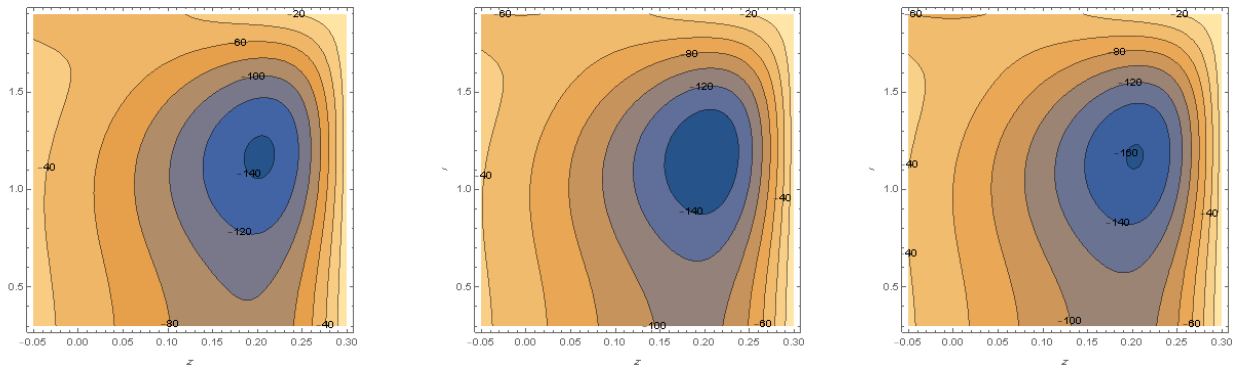


Figure 44: Wave frame streamlines for different values of $L_2 = \{0.1, 0.475, 0.625\}$ at $\varepsilon = 0.2$, $\phi = 0.2$, $\lambda_1 = 0.1$, $L_5 = 0.1$, $L_4 = 0.5$, $L_3 = 0.1$, $L_1 = 0.1$, $t = 0.05$, $Da = 0.9$, $\alpha = 3.75$, $\zeta = 0.5$, $M = 1.1$, $Gr = 2$, $\Omega = 0.9$, $Pr = 2$, $Rn = 0.5$, $Sr = 0.6$, $Sc = 0.5$, $Gc = 1$.

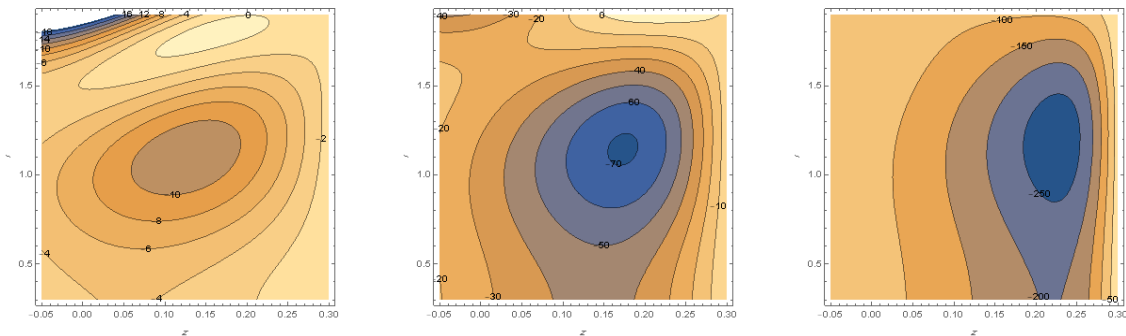


Figure 45: Wave frame streamlines for different values of $Da = \{0.1, 0.5, 0.9\}$ at $\varepsilon = 0.2$, $\phi = 0.2$, $\lambda_1 = 0.1$, $L_5 = 0.1$, $L_4 = 0.5$, $L_{31} = 0.1$, $L_1 = 0.1$, $t = 0.05$, $L_2 = 0.5$, $\alpha = 3.75$, $\zeta = 0.5$, $M = 1.1$, $Gr = 2$, $\Omega = 0.9$, $Pr = 2$, $Rn = 0.5$, $Sr = 0.6$, $Sc = 0.5$, $Gc = 1$.

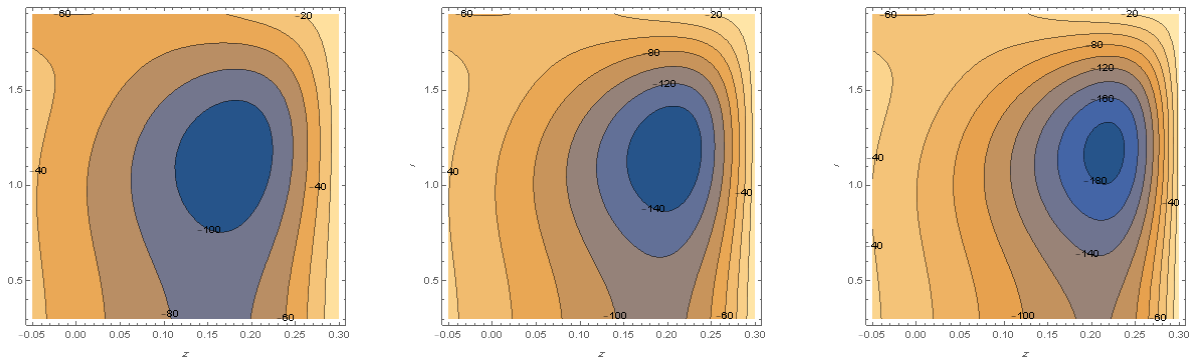


Figure 46: Wave frame streamlines for different values of $\alpha = \{3.65, 3.75, 3.8\}$ at $\varepsilon = 0.2$, $\phi = 0.2$, $\lambda_1 = 0.1$, $L_5 = 0.1$, $L_4 = 0.5$, $L_3 = 0.1$, $L_1 = 0.1$, $t = 0.05$, $L_2 = 0.5$, $Da = 0.9$, $\zeta = 0.5$, $M = 1.1$, $Gr = 2$, $\Omega = 0.9$, $Pr = 2$, $Rn = 0.5$, $Sr = 0.6$, $Sc = 0.5$, $Gc = 1$.

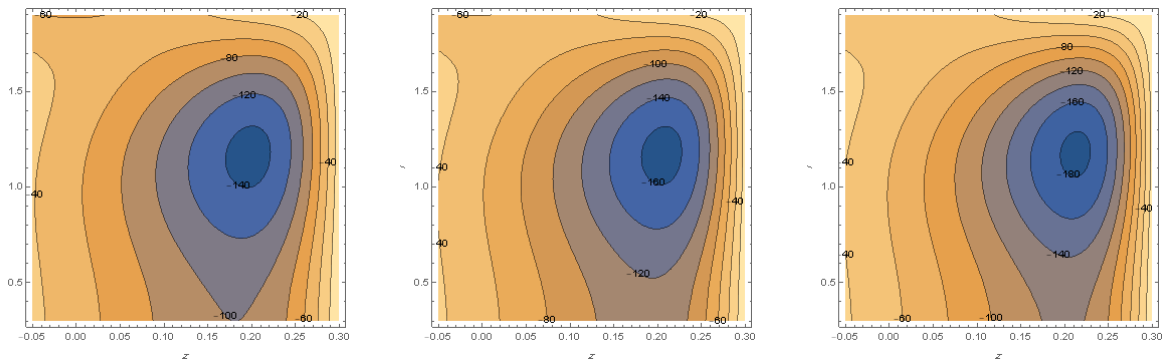


Figure 47: Wave frame streamlines for different values of $\zeta = \{0.425, 0.525, 0.625\}$ at $\varepsilon = 0.2$, $\phi = 0.2$, $\lambda_1 = 0.1$, $L_5 = 0.1$, $L_4 = 0.5$, $L_3 = 0.1$, $L_1 = 0.1$, $t = 0.05$, $L_2 = 0.5$, $Da = 0.9$, $\alpha = 3.75$, $M = 1.1$, $Gr = 2$, $\Omega = 0.9$, $Pr = 2$, $Rn = 0.5$, $Sr = 0.6$, $Sc = 0.5$, $Gc = 1$.

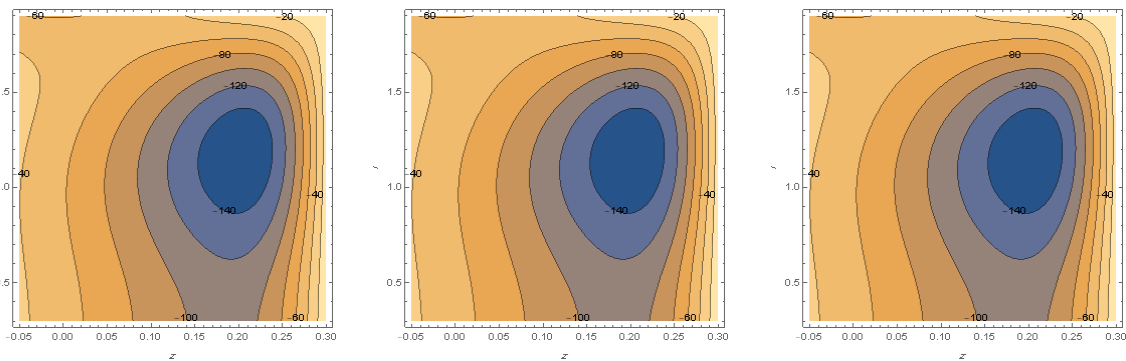


Figure 48: Wave frame streamlines for different values of $M = \{1.1, 1.2, 1.3\}$ at $\varepsilon = 0.2$, $\phi = 0.2$, $\lambda_1 = 0.1$, $L_5 = 0.1$, $L_4 = 0.5$, $L_3 = 0.1$, $L_1 = 0.1$, $t = 0.05$, $L_2 = 0.5$, $Da = 0.9$, $\alpha = 3.75$, $\zeta = 0.5$, $Gr = 2$, $\Omega = 0.9$, $Pr = 2$, $Rn = 0.5$, $Sr = 0.6$, $Sc = 0.5$, $Gc = 1$.

Remarks:

Important results were found by studying the effects of wall properties on the peristaltic flow of a couple-stress for Jeffrey fluid. Having solved the problem using the Bessel functions, we used the MATHEMATICA program to discuss the effect of efferent parameters on fluid motion by analyzing the obtained graphs. Here is a summary of the results we obtained

- The temperature of fluid rising with an increase of Ω , ε , Rn , Pr and t , while going down with the increasing ϕ .
- The Concentration of fluid rising with an increase of Ω , ε , Sr , Sc , Rn , Pr and t , while going down with the increasing ϕ .

- The velocity of fluid rise up by increasing of ϕ , L_5 , L_4 , L_1 , L_2 , Da , and α , when $r < 0.2$, while go down otherwise. The velocity of fluid go down by increasing of λ_1 , L_3 , t , M , Gr , Gc and Rn when $r < 0.2$, while rise up otherwise. The velocity of fluid go down by increasing of ζ , Ω , Pr , Sr and Sc .
- The size of the trapped bolus increases with the increasing ϕ , L_5 , L_4 , L_1 , L_2 , Da , α and ζ in the middle of the channel and the bolus will turn into a wave.
- The size of the trapped bolus decreases with the increasing ε , λ_1 , L_3 , M and t in the middle of the channel and the wave will turn into a bolus.

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