## Al-Qadisiyah Journal of Pure Science

Volume 26 | Number 2

Article 2

4-7-2021

# An Efficient Technique for Solving Bratu Type Equation via Wavelet Orthonormal Boubakerpolynomials

Eman Hassan Ouda

Department of applied sciences, university of technology, Iraq, Baghdad, 100032@uotechnology.edu.iq

Follow this and additional works at: https://qjps.researchcommons.org/home

Part of the Mathematics Commons

#### **Recommended Citation**

Ouda, Eman Hassan (2021) "An Efficient Technique for Solving Bratu Type Equation via Wavelet Orthonormal Boubakerpolynomials," Al-Qadisiyah Journal of Pure Science: Vol. 26: No. 2, Article 2. DOI: 10.29350/qjps.2021.26.2.1263

Available at: https://qjps.researchcommons.org/home/vol26/iss2/2

This Article is brought to you for free and open access by Al-Qadisiyah Journal of Pure Science. It has been accepted for inclusion in Al-Qadisiyah Journal of Pure Science by an authorized editor of Al-Qadisiyah Journal of Pure Science. For more information, please contact bassam.alfarhani@qu.edu.iq.



# An Efficient Technique for Solving Bratu Type Equation via Wavelet Orthonormal Boubaker polynomials

Authors Names	ABSTRACT		
Eman Hassan Ouda <sup>a</sup>			
	The aim of this research is to show the applicability of new truncated		
Article History	orthonormal Boubaker wavelet polynomials (OBWP's) for solving one		
Received on: 13/1 /2021 Revised on: 6/2 /2021 Accepted on: 9/2/ 2021	dimensional Bratu-type equation with $\lambda$ =-2 and $\lambda$ =2 numerically by the		
	aid of iteration technique. Some numerical examples were solved to		
Keywords:	show the ability of this kind of polynomials comparing with exact results		
Bratu-Type Equation, Wavelet	using Matlab. Also illustrating graphs were added to verify the efficiency		
Orthonormal Boubaker Polynomial, Newton Iteration Method.	of the method.		
<b>DOI:</b> https://doi.org/10.29350/			
jops.2021.26. 2.1263			

### 1. Introduction

Bratu's equation represents one of many important problems in science and engineering applications (e.g., heat transfer, chemical reactor theory, nanotechnology ...etc.)[1, 2].

The general form of Bratu-type Equation is

 $\Delta u + \lambda e^{u} = 0 \qquad \dots (1)$  $u(0) = 0 \text{ on } \delta \Omega$ 

where  $\delta\Omega$  is the boundary of a region  $\Omega$  and  $\lambda > 0$ .

This equation can be defined by a 1-dimensional planar Bratu boundary value problem as follows [3].

 $u_{xx} + \lambda e^u = 0 \qquad 0 < x < 1, \lambda > 0$ 

u(0) = u(1) = 0

which has the following exact solution

$$u(x) = -2\ln\left[\frac{\cosh\left((x-0.5)\frac{\theta}{2}\right)}{\cosh\left(\frac{\theta}{4}\right)}\right], \text{ where } \cosh\theta = \sqrt{2\lambda} \cosh\left(\frac{\theta}{4}\right),$$

The value of  $\lambda$  determines the number of solutions for this kind of equations such that

If  $\lambda < \lambda_c$ , there would be two solutions. Where  $\lambda_c$  represents the critical value.

If  $\lambda = \lambda_c$  , one solution and no solution when  $\lambda > \lambda_c$  .

For this type of Bratu equation  $\lambda_c$  has been found to be equal to 3.513830719.

For the 2-dimensional case no exact solution has been found to the Eq. 1 (see Mohsen)[4],

This type of equations is defined as follows

 $u_{xx} + u_{yy} + ce^u = 0$ 

On the region  $\Omega$ , where  $x \in [0,1]$ ,  $y \in [0,1]$ , and the boundary condition on  $\delta \Omega$  is u = 0

The same as in 1-dimensional planar Bratu boundary value case , the equation has one solution for  $\lambda = \lambda_c$ , two solutions for  $\lambda < \lambda_c$  and no solution for  $\lambda > \lambda_c$ , for small  $\lambda_c$  the equation represents a steady state heat transfer while for  $\lambda > \lambda_c$  this thermal reaction will end with explosion which represents no solution for Bratu's equation [5].

 $\lambda_c$  was found to be approximately 6.808124423.

This kind of equations has been solved by many mathematicians using different proceedings. Buckmire R., studied nonstandard finite difference method which is known as Mickens finite difference method and comparing with other methods (standard finite difference Boyd collocation, Adomian polynomial decomposition and shooting) for solving 1D planar Bratu boundary value problem[6]. Syam M. I. and Hamdan A. introduced a method based on the Laplace Adomian Decomposition method with a predictor corrector technique to demonstrate the founded solution curve [7]. Batiha B., applied the variational iteration method without discretization using a correction functional with Lagrange multiplier, finding its optimality by the aid of variational theory, this method can be used in nonlinear problems without small perturbation or linearization, it is proved to have faster convergence than Adomian's method [8, 9]. Venkatesh S. G., Ayyaswamy S. K. and Hariharan G., used Haar wavelet method for solving 1D Bratu-type equation [10]. Rashidinia J. and Taher N., utilized sinc-collocation method for solving Bratu's problem which was already presented by professor Stenger in 1993[5]. Changgang Y. and Jiahhua H., used Chebyshev wavelets with collocation method for solving 1D Bratu problem [11]. Hassan H. N. And Semary M., presented analytic approximate solutions using homotopy analysis method [12]. Saravi M., Hermann M. and Kaiser D., used He's variational iteration method with three terms in expansion of nonlinear part for solving Bratu's boundary value problem [13]. Zarebnia and Hoshyar used a non-polynomial cubic spline method for solving the Bratu equation [14]. Mohsen A. presented a good survey of the properties and different treatments of 1D and 2D Bratu problems, using finite – difference and nonstandard finite difference for solving this equation with a simple starting function for this object [4]. Inc M. et al, used the reproducing kernel Hilbert space method RKHSM (a functional analysis proceeding), which has given accurate results with respect to other known methods (Adomian decomposition, Laplace decomposition, B-spline, Non-polynomial spline and Lie-group shooting method), this method was already used by researchers for finding a solution to boundary value problems[15]. Bougoffa L. extracted a new exact solution for the generalized Bratu equation under suitable conditions of  $\lambda(x)$  and f(x) [16]. Ghomanjani F. and Shateyi S. used Bernstein polynomial approximation for solving 1D Bratu-type equation [17].

Many researchers have widely utilized Boubaker's polynomials which have first appeared for solving heat equation inside physical model [18], then many attempts have been done to construct its wavelets by the following researchers. Ouda E. H., founded the orthonormal family for Boubaker polynomials using Gram-Schmidt method then the deduction of the operational matrices of derivative and integration and using them for solving optimal control problem by indirect method [19]. Ouda E. H., Shihab S. and Rasheed M., used the properties of Boubaker orthonormal polynomials for constructing the new Boubaker wavelet orthonormal functions, founding its operational matrix of derivative then utilizing it with collocation method for transforming a higher order integro-differential equation into linear algebraic equations which can easily be solved [20].

Bratu-type equation was already studied by many researchers as we have seen from the brief summary above. This kind of numerical method proceeding gives only the lower branch solution of Bratu-type equation for  $\lambda < \lambda_c$ . In this paper, we introduced a method for solving 1D initial and boundary value problem of Bratu equations to show the capability of OBWP's for this aim.

In this paper, we have been introduced a method for solving1D initial and boundary value problem of Bratu equations. The paper is arranged as follows, in section 2 we present the wavelet orthonormal Boubaker polynomials. In section3, the standard newton iterative method for nonlinear system is introduced. Numerical examples with comparison with the exact results, and illustrative graphs have been added in section 4. Finally, the conclusions, in section5.

#### 2. Orthonormal Boubaker Polynomials:

The Boubaker orthonormal polynomials were deduced using Gram-shmidt method, it is denoted by  $\beta o_m(t)$  of order *m* and defined as follows [19]

$$Bo_{0}(t) = 1$$
  

$$Bo_{1}(t) = 2\sqrt{3}(t - \frac{1}{2})$$
  

$$Bo_{2}(t) = 6\sqrt{5}(t^{2} - t + \frac{1}{6})$$
  

$$Bo_{3}(t) = 20\sqrt{7}(t^{3} - \frac{3}{2}t^{2} + \frac{3}{5}t - \frac{1}{20})$$
  

$$Bo_{4}(t) = 70\sqrt{9}(t^{4} - 2t^{3} + \frac{9}{7}t^{2} - \frac{2}{7}t + \frac{1}{70})$$

In general, the *m*-th order orthonormal Boubaker polynomial can be obtained using the following binomial expansion.

$$Bo_m(t) = (2m+1)^{\frac{1}{2}} \sum_{k=0}^m \frac{(-1)^{m+k}(m+k)!}{k! \left[(m-k)!\right]^2} t^k$$

#### 3. Orthonormal Boubaker Wavelet [20]

The orthonormal Boubaker wavelet polynomials have been found by the aid of orthonormal Boubaker polynomials, it can be defined as

$$Bw_{n,m}(t) = Bw(k, n^*, m, t)$$

have four arguments  $k = 1, 2, ..., n^* = 2n - 1, n = 1, 2, ... 2^{k-1}$ 

*m* is the order of Boubaker orthonormal polynomials.

$$Bw_{n,m}(t) = \begin{cases} 2^{\frac{k-1}{2}} Bo_m(2^k t - n^*) & t \in [\frac{n^*-1}{2^k}, \frac{n^*+1}{2^k}) \\ 0 & othrwise \end{cases} \dots (2)$$

Where  $Bo_m$  are Boubaker orthonormal polynomials.

#### 4. Orthonormal Boubaker wavelet operation matrix of derivatives

Let Bw(t) be the Boubaker orthonormal wavelet vector presented in Eq. (2), and then Bw(t) can be written as

$$\frac{dBw(t)}{dt} = DBw(t)$$

where D is the  $2^{k}(M + 1)$  operational Matrix of the derivatives expressed as

$$D = \begin{bmatrix} D1 & 0 & \dots & 0 \\ 0 & D1 & \dots & 0 \\ \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & \ddots & D1 \end{bmatrix}$$

where  $D_1$  is an  $(M+1)\times(M+1)$  matrix and expressed as follows:

$$D_1 = 2^{K+1} \sqrt{(2m+1)} \begin{bmatrix} 0 & 0 & 0 & 0 & 0 \\ 1 & 0 & 0 & 0 & 0 \\ 0 & \sqrt{3} & 0 & 0 & 0 \\ 1 & 0 & \sqrt{5} & 0 & 0 \\ 0 & \sqrt{3} & 0 & \sqrt{7} & 0 \\ 1 & 0 & \sqrt{5} & 0 & \sqrt{9} \end{bmatrix}$$

*m* represents Boubaker orthonormal order.

then

$$\frac{d^{n}Bw(t)}{dt^{n}} = D^{n}Bw(t), \ n = 1,2,3,\dots \qquad \dots (3)$$

#### 5. The proposed method:

In this method, the modification is using Newton's iteration with different new terms of orthonormal wavelet Boubaker polynomial for each step.

The method in steps would be as follows

1- Assuming  $u(t) = \sum_{m=0}^{M-1} c_{n,m} B w_{n,m}$ , with M = 4, k = 1. where  $C = [c_{10}, c_{11}, \dots, c_{1,M-1}, c_{20}, c_{21}, \dots, c_{2,M-1,\dots,} c_{2^{k-1},0}, c_{2^{k-1},1}, \dots, c_{2^{k-1},M-1}]$ .  $Bw = [Bw_{10}, Bw_{11}, \dots, Bw_{1,M-1}, Bw_{20}, Bw_{21}, \dots, Bw_{2,M-1}, \dots, Bw_{2^{k-1},0}, Bw_{2^{k-1},1}, \dots, Bw_{2^{k-1},M-1}]$ . Bw represents orthonormal Boubaker wavelet polynomials.

2- For the 1<sup>st</sup> iteration, using Eq.3 with 2<sup>nd</sup> order differentiation of orthonormal Boubaker wavelet polynomials, then Eq.1 becomes

$$C^{T}D^{2}Bw(t) + \lambda e^{C^{T}Bw(t)} = 0 \qquad \dots (4)$$

3-The suggested collocation points can be found according to

$$t_{i} = \frac{1}{2} \left[ 1 + \cos\left(\frac{(i-1)\pi}{2^{k-1}M - 1}\right) \right],$$
  
$$i = 2, 3, \dots, 2^{k-1}M - 1 \qquad \dots (5)$$

These points are substituted in Eq.4 to find the collocated equations.

4- Using the boundary conditions equations with the collocated equations gives us a system of *M*-nonlinear equations.

5- Assuming initial values for the C's then using Newton's method the values of C's for u can be found for the 1<sup>st</sup> iteration.

6- Repeating the same procedure for the following iterations with M = 5, 6 and k = 1 to find the new approximate u.

In non-homogeneous case the same method can be used.

#### 6. Numerical Examples

#### Example1

Consider the initial value Bratu's problem

$$u''-2e^u=0$$

$$u(0) = u'(0) = 0.$$

with  $u_{exact} = -2 \ln(\cos t)$ 

Assuming  $u(t) = \sum_{m=0}^{3} c_{n,m} B w_{n,m}$ , with M = 4, k = 1, then

$$u(t) = c_{10} + \sqrt{3}c_{11}(4t - 3) + \sqrt{5}c_{12}(24t^2 - 36t + 13) + \sqrt{7}c_{13}(160t^3 - 360t^2 + 264t - 63)$$

$$\dots (6)$$

According to Eq. (6) the initial condition equations would be

$$u(0) = 0 = c_{10} - 3\sqrt{3}c_{11} + 13\sqrt{5}c_{12} - 63\sqrt{7}c_{13} \dots (7)$$
  
$$\dot{u}(0) = 0 = 4\sqrt{3}c_{11} - 36\sqrt{5}c_{12} + 264\sqrt{7}c_{13} \dots (8)$$
  
and

 $u''(t) = 48\sqrt{5}c_{12} + \sqrt{7}c_{13}(960t - 720).$ 

Using Eq. (5), the collocation points would be 0.25, 0.75 for i=2, 3.

Let  $F = u'' - 2e^u$ 

We have now the following system of four equations with Eq. (7) and (8) with C's as unknowns

$$F(0.25) = 48\sqrt{5}c_{12} - 2e^{\left(c_{10} - 2\sqrt{3}c_{11} + \frac{(11\sqrt{5}c_{12})}{2} - 17\sqrt{7}c_{13}\right)} - 480\sqrt{7}c_{13} = 0.06316210$$
  
$$F(0.75) = 48\sqrt{5}c_{12} - 2e^{\left(c_{10} - \frac{(\sqrt{5}c_{12})}{2}\right)} = 0.62479979$$

To find C's, using Newton's method from assumed initial values of C's, we obtain: for the  $1^{st}$  iteration (M = 4, k = 1) the following results

 $c_{10}$ =0.651173917794325,  $c_{11}$ =0.277886089393695,  $c_{12}$ =0.034390517276518,

#### *c*<sub>13</sub>=0.001241459639318.

~ ~ -

....

and

$$u_1(t) = \frac{319}{607}t^3 + \frac{313}{472}t^2 + \frac{260}{10833}t - 5.807377148614457e - 14$$

In the same way for the  $2^{nd}$  iteration (M = 5, k = 1), we get the following results  $c_{10}$ =0.669917696510561,  $c_{11}$ =0.276857334675699,  $c_{12}$ =0.035454448724780,  $c_{13}$ =0.002351369914077,  $c_{14}$ =0.000134980050874.

$$u_2(t) = \frac{1181}{2604}t^4 - \frac{3593}{9838}t^3 + \frac{2029}{1735}t^2 - \frac{250}{11153}t + 1.188229473581687e - 13$$

Also in the same way for the  $3^{rd}$  iteration (M = 6, k = 1), we get the following results *c*<sub>10</sub>=0.663632989760171, *c*<sub>11</sub>=0.273895474804654, *c*<sub>12</sub>=0.034694806839367, . . . . . . . . . . . . . . . . . . . 

$$c_{13}$$
=0.002228815444385,  $c_{14}$ =0.000133676822432,  $c_{15}$ =0.000007363658178.

$$u_3(t) = \frac{335}{1701}t^5 - \frac{193}{4437}t^4 + \frac{303}{3400}t^3 + \frac{801}{814}t^2 + \frac{28}{19095}t + 1.004644626954481e - 13$$

~ ~

t	u(t)(M=4)	u(t)(M=5)	u(t)(M=6)	u(t) <sub>exact</sub>
0	-5.8064664e-14	0.000000000	0.000000000	0.000000000
0.1	0.0095569606	0.0091225748	0.0100736698	0.0100167112
0.2	0.0355298345	0.0399101953	0.0403608259	0.0402695461
0.3	0.0810718314	0.0916592487	0.0915349966	0.0913833118
0.4	0.1493361610	0.1648543777	0.1646379784	0.1644580381
0.5	0.2434760331	0.2611684808	0.2613161678	0.2611684808
0.6	0.3666446574	0.3834627120	0.3840568926	0.3839303388
0.7	0.5219952437	0.5357864807	0.5364247436	0.5361715151
0.8	0.7126810015	0.7233774520	0.7232979062	0.7227814936
0.9	0.9418551408	0.9526615466	0.9511044919	0.9508848871
1	1.2126708712	1.2312529407	1.2280588698	1.2312529407

The approximate results for u(t) are shown in table (1) with comparison to the exact results.

Table (1) Numerical solution of Example 1

Fig.1 illustrates the approximate results with the exact solution, which shows a good accuracy results.



Figure1 Graphical illustration of Example1

### Example2

Consider the nonlinear Bratu's problem

$$\begin{split} u''+2e^u &= 0 \ , \\ \text{with } u(0) &= u(1) = 0 \ . \\ \text{The exact is } u_e(t) &= 2\ln(\frac{1.17877552}{\cosh(0.58938776*(1-2t)\,)}) \end{split}$$

Assuming  $u(t) = \sum_{m=0}^{3} c_{n,m} B w_{n,m}$ , with M = 4, k = 1, then  $u(t) = c_{10} + \sqrt{3}c_{11}(4t - 3) + \sqrt{5}c_{12}(24t^2 - 36t + 13) + \sqrt{7}c_{13}(160t^3 - 360t^2 + 264t - 63)$ ...(9)

According to Eq. (9) the initial condition equations would be

$$u(0) = 0 = c_{10} - 3\sqrt{3}c_{11} + 13\sqrt{5}c_{12} - 63\sqrt{7}c_{13} \dots (10)$$
$$u(1) = 0 = c_{10} + \sqrt{3}c_{11} + \sqrt{5}c_{12} + \sqrt{7}c_{13} \dots (11)$$
and

 $u''(t) = 48\sqrt{5}c_{12} + \sqrt{7}c_{13}(960t - 720).$ Let  $F = u'' + 2e^u$ .

We have now the following system of four equations with Eq.(10) and (11) with C's as unknowns

$$F(0.125) = 2e^{\left(c_{10} - \frac{(5\sqrt{3}c_{11})}{2} + \frac{(71\sqrt{5}c_{12})}{8} - \frac{(565\sqrt{7}c_{13})}{16}\right)} + 48\sqrt{5}c_{12} - 600\sqrt{7}c_{13} = 0.13960278$$

$$F(0.5) = 2e^{\left(c_{10} - \sqrt{3}c_{11} + \sqrt{5}c_{12} - \sqrt{7}c_{13}\right)} + 48\sqrt{5}c_{12} - 240\sqrt{7}c_{13} = 0.32895242$$

To find C's, using Newton's method from assumed initial values of C's, we obtain the following results for the  $1^{st}$  iteration (*M*=4, *k*=1)

 $c_{10}$ =0.246962736146410,  $c_{11}$ =-0.102089915668847,  $c_{12}$ =-0.030575992704274,  $c_{13}$ =-0.000668172059051.

$$u_1(t) = -\left(\frac{193}{1835}\right)t^3 - \left(\frac{1634}{1411}\right)t^2 + \left(\frac{1051}{832}\right)t - 8.078401229211218e - 14$$

In the same way for the 2<sup>nd</sup> iteration (M = 5, k = 1), we get the following results,  $c_{10}=0.216749920799177, c_{11}=-0.096081625621780, c_{12}=-0.023458207575246,$  $c_{13}=0.000708938658435, c_{14}=0.000087281006539.$ 

$$u_2(t) = \left(\frac{1055}{3597}\right)t^4 - \left(\frac{331}{571}\right)t^3 - \left(\frac{890}{927}\right)t^2 + \left(\frac{450}{361}\right)t - \frac{12}{791797}$$

Also in the 3<sup>rd</sup> iteration (M = 6, k = 1), we get the following results  $c_{10}=0.216843539460207$ ,  $c_{11}=-0.096090113273145$ ,  $c_{12}=-0.023465093655457$ ,  $c_{13}=0.000707174078480$ ,  $c_{14}=0.000086979774672$ ,  $c_{15}=-0.000000087426089$ .

$$u_3(t) = -\left(\frac{62}{26511}\right)t^5 + \left(\frac{911}{3056}\right)t^4 - \left(\frac{585}{1003}\right)t^3 - \left(\frac{870}{907}\right)t^2 + \left(\frac{1885}{1512}\right)t + \frac{1}{1878680018653}$$

The results are shown in table (2) with the comparison to the exact results.

	t	u(t) (M=4)	u(t) (M=5)	u(t) (M=6)	u(t) <sub>exact</sub>	
	0	-0.000000000	-0.0000151553	0.0000000000	0.0000000000	
	0.1	0.1146364981	0.1144873323	0.1145237562	0.1144107432	
	0.2	0.2054810516	0.2067205504	0.2067805265	0.2064191164	
	0.3	0.2719025981	0.2742621431	0.2743404724	0.2738793118	
	0.4	0.3132700754	0.3153935885	0.3154835864	0.3150893642	
	0.5	0.3289524213	0.3291001989	0.3291968861	0.3289524213	
	0.6	0.3183185735	0.3150711204	0.3151716084	0.3150893642	
	0.7	0.2807374697	0.2736993335	0.2738004032	0.2738793118	
	0.8	0.2155780477	0.2060816523	0.2061745282	0.2064191164	
	0.9	0.1222092452	0.1140187254	0.1140810422	0.1144107432	
	1	0.0000000000	0.0000150351	0.000000000	0.0000000000	

Table (2) Numerical solution of Example 2

Fig.2 illustrates the approximate results with the exact solution, which shows a good accuracy results.



Figure 2. Graphical illustration of Example2

#### 7. Conclusion:

The obtained numerical results have shown the good accuracy of this method using orthonormal Boubaker wavelet polynomials (OBWP's). These results represent usually the lower branch of the solution as expected from this kind of methods, also it can be noticed that the odd iterations have more accurate results than others. From the illustrating graphs it can be seen that the numerical solutions have a good approximation to the exact with few iterations and fast convergence. This method shows the ability of OBWP's for solving nonlinear Bratu-type equation, which can be verified in the future for finding solutions of other physical nonlinear problems.

#### References

- [1] Aris R., The mathematical Theory of Diffusion and Reaction in Permeable Catalyst, Vol.1, Oxford University Press, Clarendon, (1975).
- [2] Berbernes J. and Eberly D., Mathematical Problems from Combustion Theory, Applied Mathematical Sciences, Springer-Verlag (1989).
- [3] Batiha B., "Numerical Solution of Bratu-Type Equations by the Variational Iteration Method", Vol. 39(1), Hacettepe Journal of Mathematics and Statistics, (2010), pp.23-29.
- [4] Mohsen A., "A Simple Solution of the Bratu Problem", Vol.67, ELSEVIER, Journal of Computers and Mathematics with Applications, (2014), pp. 26-33.
- [5] Rashidinia J. and Taher N., "Application of the Sinc Approximation to the Solution of Bratu's Problem", Vol.02, No.03, International Journal of Mathematical Modeling & Computations, (2012), pp.239-246.
- [6] Buckmire R., "Applications of Mickens Finite Difference to Several Related Boundary Value Problems", Advances in the Applications of Nonstandard Finite Difference Schemes Ed. R. E. Mickens, World Scientific Publishing: Singapore, (2005), pp.47-87.
- [7] Syam M. I. and Hamdan A., "An Efficient Method for Solving Bratu Equations", Vol. 176, Journal of Applied Mathematics and Computation, (2006) pp. 704-713.
- [8] Inokuti M., Sekine H. and Mura T., "General Use of the Lagrange Multiplier in Nonlinear Mathematical Physics", in: S. Nemat-Nasser (Ed.), Variational Method in the Mechanics of Solids, Pergamon Press, Oxford, (1978), pp.156-162.
- [9] Heji-Huan, "Variational Iteration Method a kind of nonlinear analytical technique: some examples", Vol.34, International Journal of Non-linear mechanics, (1999), pp.699-708.
- [10] Venkatesh S. G., Ayyaswamy S. K. and Hariharan G.," Haar Wavelet Method for Solving Initial and Boundary Value Problems of Bratu-type", Vol.4, No.7, International Journal of Mathematical and Computational Sciences, (2010).
- [11] Changqing Y. and Jianhua H., "Chebyshev Wavelets Method for Solving Bratu's Problem, Boundary Value Problems" Vol. 2013(142), (a Springer Open Journal), (2013).
- [12] Hassan H. N. and Semary M. S., "Analytic Approximate Solution for Bratu's Problem by Optimal Homotopy Analysis Method", Vol. 2013, Journal of Communications in Numerical Analysis, ISPACS, Article ID can- 00139(2013).
- [13] Saravi M., Hermann M. and Kaiser D., " Solution of Bratu's Equation by He's variational Iteration Method", Vol. 3, Issue (1), American Journal of Computational and Applied mathematics, (2013), pp. 46-48.
- [14] Zarebnia M. and Hoshyar M., "Solution of Bratu-Type Equation via Spline Method", Vol. 2014, No.37, Acta Universities Apulensis, (2014), pp.61-72.

- [15] Inc M., Akgul A. and Geng F., "Reproducing Kernel Hilbert Space Method for Solving Bratu's Problem", Vol. 38, Bulletin of the Malaysian Mathematical Sciences Society, (2015), pp.271-287.
- [16] Lazhar Bougoffa, "Exact Solution of A Generalized Bratu Equation", Vol.62, article No.110, Romanian Journal of Physics, (2017), pp.1-5.
- [17] Ghomanjani F. and Shateyi S., "A New Approach for Solving Bratu's Problem", Vol. 52, published by DE GRUYTER, (2019), pp.336-346.
- [18] Boubaker K., "On modified Boubaker polynomials: Some Differential and Analytical Properties of the New Polynomials", Vol.2 (6), Journal of Trends in Applied Science Research, (2007), pp.540-544.
- [19] Ouda Eman H., "A New Approach for Solving Optimal Control Problems Using Normalized Boubaker Polynomials", Vol. 23(1), Emirates Journal for Engineering Research, (2018), pp.7-19.
- [20] Ouda Eman H., Shihab S. and Rasheed M., "Boubaker Wavelet Functions for Solving Higher Order Integro-differential Equations", Vol.55, No.2, Journal of Southwest Jiatong University, (2020), pp.1-10.